ABSTRACT -----

One of the aims of study the fuzzy set theory is to develop the methodology of the formulations and the solutions of problems that are too complicated or ill-defined to be acceptable to analysis by conventioal techniques. Therefore, fuzziness could be considered as a type of imprecision that steams from a grouping of elements into classes that do not have exact defined boundaries. Such classes, introduced by Zadeh L. A., in 1965 as a tool used to describe the ambiguity, vagueness and ambivalence in the mathematical models.

This thesis have three objectives. The first objective is to study fuzzy sets theory and presenting the proof of some well known results in this theory This is a watermark for the trial version, register to get the full one!

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been introduced previously, as well as, some methods of solution of such type of problems.

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Also, I would like to thank my family for the care, sacrifice, respect and love during my study.

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Ammar Jaffar Al-Saedy

2006

SUPERVISOR CERTIFICATION-----

I certify that this thesis was prepared under my supervision at the Department of Mathematics and Computer Applications, College of Science, Al-Nahrain University as a partial fulfillment of the requirements for the degree of Master of Science in mathematics

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Additional theoretical concepts in fuzzy set theory could be discussed concerning fuzzy mapping, differentiation and integration of fuzzy function, etc.; and therefore are presented in this chapter for completeness. This is a watermark for the trial version, register to get the full one!

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differentiation of fuzzifying function at a non-fuzzy point.

Finally, in section four two types of fuzzy integration have been discussed, which are integration of real valued fuzzy function over closed interval and integration of crisp real valued function over fuzzy interval since of it's important in the existence and uniqueness theorem of fuzzy differential equations.

2.1 FUZZY FUNCTIONS [DUBOIS, 1980]

The term "fuzzy function" must be understood in several ways according to where fuzziness occurs. We start first with the first type:

2.1.1 Function with Fuzzy Constraint:

Let X and Y be two universal sets and let f be a classical function $f: X \to Y$ maps from a fuzzy domain \widetilde{A} in X into a fuzzy range \widetilde{B} in Y then f is a function with fuzzy constraint if for all $x \in X$, $\mu_{\widetilde{B}}(f(x)) \ge \mu_{\widetilde{A}}(x)$.

Example(2.1):

Let X = Y = R, and consider two fuzzy sets:

$\widetilde{A} = \{(1,0.5), (2,0.8)\}$ and $\widetilde{B} = \{(2,0.7), (4,0.9)\}$

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independent variables to dependent variables, when f is a crisp function from

X onto *Y*. Let \tilde{A} be a fuzzy subset of *X*, then $\tilde{B} = f(\tilde{A})$ is a fuzzy subset of *Y* with membership function defined by:

$$\mu_{\tilde{B}}(y) = \begin{cases} \sup_{x \in f^{-1}(y)} \mu_{\tilde{A}}(x), & \text{if } f^{-1}(y) \neq \emptyset \\\\ 0, & \text{if } f^{-1}(y) = \emptyset \end{cases}$$

where $f^{-1}(y)$ is the inverse image of *y*.

Example (2.2):

Consider the universal sets X = Y = R and consider a crisp function $f(x) = x^2$, with the domain given by the fuzzy set:

 $\widetilde{A} = \{(-2, 0.9), (-1, 0.6), (0, 0.7), (1, 0.8), (2, 0.5)\},\$

The independent variable x has an ambiguity and the fuzziness which is propagated to the fuzzy set \tilde{B} , then we can obtain \tilde{B} , as:

 $\widetilde{B} = \{(4, 0.9), (0, 0.7), (1, 0.8)\}.$

2.1.3 Single Fuzzifying Function :

Fuzzifying function from X onto Y is a mapping from X into the fuzzy power set $\tilde{P}(Y)$ (or I^X), i.e., $\tilde{F}: X \to \tilde{P}(Y)$, that is to say the fuzzifying function is a mapping from an ordinary domain to a fuzzy set of range, This is a watermark for the trial version, register to get the full one!

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2.1.4 Fuzzy Bunch Function:

Fuzzifying bunch of crisp functions from *X* onto *Y* is defined with fuzzy set of crisp function:

$$\tilde{f} = \left\{ (f_i, \mu_{\tilde{f}}(f_i) | f_i : X \to Y, i \in N : N \text{ is the set of natural numbers} \right\}.$$

where $\mu_{\tilde{f}}(f_i)$ is the membership function of the crisp function f_i .

Example (2.3):

$$X = \{1, 2, 3\}, \ \widetilde{f} = \{(f_1, 0.4), (f_2, 0.7), (f_3, 0.5)\}$$

where $f_1(x) = x$, $f_2(x) = x^2$, $f_3(x) = 1 - x$.

2.2 FUZZY MAPPINGS

A fuzzy mapping is a generalization of the concept of a classical mapping which can be understood as follows:

Definition (2.1)[Dubois, 1982]:

A fuzzy mapping \tilde{f} from a crisp set U onto a set V is a mapping from U to the power set of non-empty subsets V, namely $\tilde{P}(V) - \{\emptyset\}$.

In other words, to each element $u \in U$ corresponds a fuzzy set $\tilde{f}(u)$ defined

on *V*, whose membership function is $\mu_{\tilde{f}(u)}$, and $\tilde{f}(u)$ is non-empty.

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- A fuzzy set \tilde{F} of V^U , i.e., a fuzzy set of ordinary mapping from U to Veach mapping $f: U \longrightarrow V$ is assigned a membership grade $\mu_{\tilde{F}}(f)$.

Proposition(2.1)[Dubois, 1982]:

A fuzzy mapping is strictly equivalent to a fuzzy relation \widetilde{R} such that

 $\forall u \in U, \exists v \in V, \quad \mu_{\tilde{\nu}}(u, v) = 0.$

Proof: See [Dubois, 1982]. ■

<u>Remarks (2.1):</u>

- 1. As a converse of proposition (2.1), a fuzzy relation can be viewed as a fuzzy mapping if $\mu_{\tilde{p}}(u,.)$ determines a nonempty fuzzy set $\tilde{f}(u)$.
- 2. Fuzzy mappings and fuzzy relations have different points of view on the same mathematical notion.
- 3. Fuzzy set of mappings (FSM's, for short) are not equivalent to fuzzy mapping. Indeed, a natural way of assigning membership grades μ(u,v) to possible images v∈ V of u∈ U, given an FSM F, is to define μ(u,v) = μ_F(f) whenever v = f(u). Note that μ(u,v) is not uniquely defined since there may exist f, g: U → V, f ≠g, such that

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Starting from the fuzzy mapping $f: U \to V$ for any $\alpha \in [0,1]$. We can

define an ordinary multimapping f_{α} as follows:

$$f_{\alpha}(u) \!=\! \left\{ v \mid \! \mu_{\tilde{f}(u)}(v) \!\geq\! \alpha \right\} \!\subseteq\! V \,, \, \text{for all } u \!\in\! U.$$

 f_{α} is the α - cut of \tilde{f} .

Also, f_{α} can be viewed as a crisp subset of V^{U} , i.e., a set of mappings

$$\begin{split} f_{\alpha} &= \Big\{ f: U \to V \mid \forall u \in U, f(u) \in f_{\alpha}(u) \Big\} \\ &= \Big\{ f: U \to V \mid \inf_{u \in U} \mu_{\tilde{f}(u)}(f(u)) \geq \alpha \Big\}. \end{split}$$

 f_{α} is the α -cut of an FSM generated by f_{α} , denoted $\gamma(\tilde{f})$, such that

Example(2.4) [Najeib S,W., 2002]:

Let $X = \{2, 3, 4, \dots, 25\}$, a fuzzy mapping \tilde{f} maps the elements in X to the power fuzzy set $\tilde{P}(X)$ in the following manner.

$$\begin{split} \widetilde{f}(2) &= \{(2,0.3), (3,0.5), (4,1), (5,0.5), (6,0.3), (9,0.2)\} \\ \widetilde{f}(3) &= \{(3,0.3), (5,0.5), (7,1), (9,0.5), (14,0.3), (16,0.2)\} \\ \widetilde{f}(4) &= \{(4,0.3), (8,0.5), (12,1), (16,0.5), (20,0.3), (25,0.2)\} \end{split}$$

Now, given a function $f_l(x) = 2x$,

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For $f_2(x) = x^2$, we have

$$\mu_{\gamma(\tilde{f})}(f) = \inf \left\{ \mu_{\tilde{f}(x)}(f_2(x)) | x \in X \right\}$$

= $\inf \left\{ \mu_{\tilde{f}(2)}(f_2(2)), \mu_{\tilde{f}(3)}(f_2(3)), \mu_{\tilde{f}(4)}(f_2(4)) \right\}$
= $\inf \left\{ \mu_{\tilde{f}(2)}(4), \mu_{\tilde{f}(3)}(9), \mu_{\tilde{f}(4)}(16) \right\}$
= $\inf \{1, 0.5, 0.5\} = 0.5$

So,
$$\gamma(\tilde{f}) = \{(f_1, 0), (f_2, 0.5)\}$$
, where $f_1(x) = 2x$ and $f_2(x) = x^2$.

Now, to the second case which is the converse of the above construction which is also can be made as expressed in the following definition.

Definition(2.2) [Najeib S.W., 2002]:

Given a fuzzy set of mappings $\gamma(\tilde{f})$ with $\mu_{\gamma(\tilde{f})}: I^x \to [0,1]$, we can construct a fuzzy mapping $\tilde{f}: X \to \tilde{P}(X)$ such that $\tilde{f}(x)$ is a fuzzy set with membership function defined as follows :

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 $T(f) = \{(f_1, 0.2), (f_2, 0.5), (f_3, 0.7), (f_4, 0.3)\}$

where

$$f_1(x) = x, f_2(x) = x^2, f_3(x) = e^x, f_4(x) = x + 1.$$

Then the image at x = 1, is:

$$\mu_{\tilde{f}(1)}(y) = \sup \left\{ \mu_{\gamma(\tilde{f})}(f) \mid y = f(x) \right\}$$

The possible values of y is $\{f_1(1), f_2(1), f_3(1), f_4(1)\} = \{1, 1, e, 2\}$

$$\mu_{\tilde{f}(1)}(y) = \sup_{f_1, f_2} \left\{ \mu_{\gamma(\tilde{f})}(f_1), \ \mu_{\gamma(\tilde{f})}(f_2) \right\}$$
$$= \sup_{f_1, f_2} \{ 0.2, 0.5 \} = 0.5$$

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 $\mu_{\tilde{f}^{(1)}}(e) = 0.7, \ \mu_{\tilde{f}^{(1)}}(2) = 0.3$

So the fuzzy set $\tilde{f}(1) = \{(1,0.5),(2,0.3),(e,0.7)\}$

Similarly

$$\tilde{f}(2) = \{(2,0.2), (4,0.5), (e^2, 0.7), (3,0.3)\}$$

 $\tilde{f}(3) = \{(3,0.2), (9,0.5), (e^3, 0.7), (4,0.3)\}.$

Hence:

$$\widetilde{f}(x) = \left\{ \left(f(x), \sup\{\mu_{\gamma(\widetilde{f})}(f) \mid y = f(x), f \in \gamma(\widetilde{f})\} \right) \right\}, \text{ for all } x \in X.$$

Lemma (2.1) [Dubois, 1982]:

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inf min { $\mu_{\tilde{f}(u)}(f(u)), \mu_{\tilde{g}(u)}(g(u))$]

 $f,g:h(u)=f(u)+g(u) \ u\in U$

$$\leq \inf_{u \in U} \sup_{f,g:h(u)=f(u)+g(u)} \min \left(\mu_{\tilde{f}(u)}(f(u)), \mu_{\tilde{g}(u)}(g(u)) \right),$$

and since for any mapping $\varphi:A \times B \rightarrow R$.

 $\inf_x \sup_y \varphi(x,y) \ge \sup_x \inf_y \varphi(x,y),$

hence,

$$\begin{split} \mu_{\gamma(f)\oplus\gamma(g)}(\mathbf{h}(\mathbf{u})) &\leq \inf_{u\in U} \mu_{\gamma(f\oplus g)(u)}(h(u)) \\ &\leq \mu_{\gamma(\tilde{f}\oplus\tilde{g})(u)}h(u). \quad \blacksquare \end{split}$$

2.3 FUZZY DIFFERENTIATION [DUBOIS, 1982]

The fuzzy differentiation depends on the type of the considered function in section (2.1), i.e., differentiation of non-fuzzy function over fuzzy interval and that of fuzzifying function at non-fuzzy points, may be considered as a type of fuzzy differentiation.

2.3.1 Differentiation of Crisp Function on Fuzzy Points:

By the extension principle, differentiation $f'(\tilde{A})$ of a non-fuzzy function f at fuzzy point \tilde{x}_0 [Dubois, 1982b] is defined as:

 $\mu_{f'(\tilde{x}_0)}(y) = Max \ \mu_{\tilde{x}_0}(x)$

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then $f'(x) = 3x^2$ and therefore:

$$f'(\widetilde{A}) = \{(3, 0.4), (0, 1), (3, 0.6)$$
$$= \{(3, 0.6), ((0, 1))\}$$

2.3.2 Differentiation of Fuzzifying Function Over a Set of Non-Fuzzy Points:

For all x belongs to the ordinary domain D, we will define the differentiation of fuzzifying function \tilde{f} at a non-fuzzy point. Let any α -cut of \tilde{f} be differentiable for an arbitrary x in D, we define differentiation $(d\tilde{f}/dx)(x_0)$ at an ordinary point x_0 as:

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$$\mu_{\left(d\tilde{f}/dx\right)(x_{0})}(p) = \max_{\left(d\tilde{f}_{\alpha}/dx\right)(x_{0})=p} \mu_{\tilde{f}}(\tilde{f}_{\alpha})$$

The next example illustrates the above definition:

Example (2.7):

Consider the fuzzifying function:

 $\tilde{f} = \{(f_1, 0.4), (f_2, 0.7), (f_3, 0.4)\}$

where f_1, f_2 and f_3 are crisp functions defined by:

$$f_1(x) = x, f_2(x) = x^2$$
 and $f_3(x) = x^3 + 1$

Then $f_1'(x) = 1, f_2'(x) = 2x$ and $f_3'(x) = 3x^2$

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$$f_3'(0.5) = 0.75$$
, when $\alpha = 0.4$.

Hence:

$$\frac{d\tilde{f}}{dx}(x_0) = \max\{(1, 0.4), (1, 0.7), (0.75, 0.4)\}\$$
$$=\{(1, 0.7), (0.75, 0.4)\}.$$

Another type of fuzzy differentiation which is called the *L- R type* could be used also in differentiating fuzzy functions (for more details, see, e.g., [Dubois, 1982]).

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2.3.3 Algebraic Properties of Differentiation

As in non-fuzzy differentiation so many properties are given and proved successfully. Therefore, similarly several algebraic properties undertaking fuzzy differentiation could be given. The proofs will be given here for the sake of completeness.

We start first with the following theorem:

<u>Theorem (2.1):</u>

The extended sum \oplus of the derivatives of the real valued functions *f* and *g* at the fuzzy point \tilde{x}_0 is defined by:

 $f'(\widetilde{x}_0) \oplus g'(\widetilde{x}_0) \supseteq (f' + g')(\widetilde{x}_0)$

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Theorem (2.2):

If f' and g' are continuous and both non-decreasing (or non-increasing), then:

 $f'(\widetilde{x}_0) \oplus g'(\widetilde{x}_0) = (f' + g')(\widetilde{x}_0)$

Proof: See [Dubois, 1982]. ■

The next theorem illustrates the differentiation of product of two functions, which is given in [Dubois, 1982] and other literatures without proof (to the best of our knowledge); which will be presented here for completeness:

Theorem (2.3):

1. If f and g are crisp functions from X to Y and \tilde{x}_0 is a fuzzy point in X then:

$$(fg)'(\widetilde{x}_0) = (f'g + fg')(\widetilde{x}_0) \subseteq [f'(\widetilde{x}_0) \square g(\widetilde{x}_0)] \oplus [f(\widetilde{x}_0) \square g'(\widetilde{x}_0)].$$

2. If f, g, f' and g' are continuous, f and g are both positive, and f' and g' are both non-decreasing (f, g are negative and f', g' are non decreasing), then:

$$(fg)'(\widetilde{x}_0) = [f'(\widetilde{x}_0) \Box g(\widetilde{x}_0)] \oplus [f(\widetilde{x}_0) \Box g'(\widetilde{x}_0)]$$

Proof:

1. According to the properties of fuzzy set, we must prove that:

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$$= \sup_{s,t:y=f'(s)g(s)+f(t)g'(t)} \min \left\{ \mu_{\tilde{x}_0}(s), \ \mu_{\tilde{x}_0}(t) \right\} ..(2.3)$$

Also, using the extension principle to the left hand side, one can get:

Now, from equations (2.3) and (2.4), we have:

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$$\sup_{x:y=f'(x)g(x)+f(x)g'(x)} \mu_{\tilde{x}_0}(x) \le \sup_{s,t:y=f'(s)g(s)+f(t)g'(t)} \min\left\{\mu_{\tilde{x}_0}(s), \ \mu_{\tilde{x}_0}(t)\right\}$$

Since $\tilde{x_0}$ is a fuzzy point which has a supremum value therefore,

$$(fg)'(\widetilde{x}_0) = (f'g + fg')(\widetilde{x}_0) \subseteq [f'(\widetilde{x}_0) \square g(\widetilde{x}_0)] \oplus [f(\widetilde{x}_0) \square g'(\widetilde{x}_0)].$$

2. Since f' and g' are continuous on [a, b] and both non decreasing in [a, b], then:

$$\forall s, \forall t > s, \exists x \in [s,t] \subseteq [a,b]$$
, such that:

$$f'(x) g(x) + f'(x) g'(x) = f'(s) g(s) + f(t) g'(t).$$

Hence in particular:

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$$\mu_{\tilde{x}_0}(x) \geq \min\left\{\mu_{\tilde{x}_0}(s), \mu_{\tilde{x}_0}(t)\right\}$$

Hence:

$$\mu_{\left[f'(x_0')\square g(\tilde{x_0})\right] \oplus \left[f(\tilde{x_0})\square g'(\tilde{x_0})\right]}(y) =$$

$$\sup_{\substack{u,v:y=u+v \\ x:y=f'(x)g(x)+f(x)g'(x) \\ x:y=f'(x)g(x)+f(x)g'(x) \\ x:y=f'(x)g(x) \\ x:y=f'(x)g(x) \\ x:y=f'(x)g(x) \\ x:y=f'(x)g'(x) \\ x:y=f'(x)g'(x)g'(x) \\ x:y=f'(x)g'(x) \\ x:y=f'(x)g'(x)g'(x) \\ x:y=f'(x)g'(x$$

$$= \sup_{x:y=f'(x)g(x)+f(x)g'(x)} \mu_{\tilde{x}_0}(x).$$

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Therefore;

$$\mu_{[f'(x_0')\square g(\tilde{x_0})] \oplus [f(\tilde{x_0})\square g'(\tilde{x_0})]}(y) = \sup_{x: y = f'(x)g(x) + f(x)g'(x)} \mu_{\tilde{x_0}}(x).$$

But;

$$\mu_{(f,g)'(\tilde{x}_0)}(y) = \mu_{[f',g+f,g'](\tilde{x}_0)}(y) = \sup_{x:y=f'(x),g(x)+f(x),g'(x)} \mu_{\tilde{x}_0}(y)$$

Then:

$$(f g)'(\tilde{x}_0) = [f'(\tilde{x}_0) \Box g(\tilde{x}_0)] \oplus [f(\tilde{x}_0) \Box g'(\tilde{x}_0)]. \blacksquare$$

2.4 FUZZY INTEGRATION

The fuzzy integration is one of the most important part of the analysis of This is a watermark for the trial version, register to get the full one!

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Integration of real fuzzy function over fuzzy interval.

The first two of the above three types will be discussed next:

2.4.1 Integration of Real Fuzzy Function over Crisp Closed Interval

[Dubois, 1982]

We shall now consider a fuzzy function f, which shall be integrated over the crisp interval [a,b].

Definition(2.3):

Let $\tilde{f}: X \to \tilde{F}(\mathbb{R})$, the integral of \tilde{f} over X = [a,b] denoted by $\int_{\mathbb{R}} \tilde{f}(t) dt$ is defined levelwise, as follows:

$$\left(\int_{X} \tilde{f}(t)dt\right)_{\alpha} = \int_{X} f_{\alpha}(t)dt, \text{ for all } 0 \le \alpha \le 1$$
$$= \left(\int_{X} f_{\alpha^{-}}(t)dt, \int_{X} f_{\alpha^{+}}(t)dt\right)....(2.5)$$

Remark (2.2):

If the fuzzy integration over the interval X = [a,b] is reversed from *b* to *a*. This is a watermark for the trial version, register to get the full one!

Benefits for registered users: 1.No watermark on the output documents. 2.Can operate scanned PDF files via OCR. 3.No page quantity limitations for converted PDF files. where $-\int \tilde{f}$ has for a membership function $\mu_{a}(u) = \mu_{b}(-u)$.

Following, some properties of the integration of fuzzy function over crisp interval which are given in [Dubois, 1982].

1.
$$\int_{X} (\tilde{f} \oplus \tilde{g}) \supseteq \left(\int_{X} \tilde{f} \right) \oplus \left(\int_{X} \tilde{g} \right)$$
, where \tilde{f} and \tilde{g} are real fuzzy functions from

the closed interval X to R, with bounded support.

2. Under the commutativity condition for \int_X and \oplus ,

$$\int_{X} (\tilde{f} \oplus \tilde{g}) = \left(\int_{X} \tilde{f} \right) \oplus \left(\int_{X} \tilde{g} \right)....(2.6)$$

Example(2.8):

Consider the bunch fuzzy function given in (2.1.4), by:

$$\tilde{f} = \{(f_1, 0.4), (f_2, 0.7), (f_3, 0.4)\}$$

where

$$f_1(x) = x, f_2(x) = x^2, f_3(x) = x+1$$

and to integrate this bunch function over [1,2], we perform this as follows:

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Hence, the integration result is with possibility 0.7, is given by:

$$\tilde{I}_{0.7}(1,2) = \{(\frac{7}{3}, 0.7)\}.$$

ii) Integration at $\alpha = 0.4$, there are two functions

$$f^{+} = f_1(x) = x$$
 and $f^{-} = f_3(x) = x+1$, then for

$$I^{+}_{\alpha}(1,2) = \int_{1}^{2} x dx = \frac{1}{2} x^{2} \bigg]_{1}^{2} = \frac{3}{2}.$$

and

$$I_{\alpha}^{-}(1,2) = \int_{1}^{2} (x+1)dx = \frac{1}{2}x^{2} + x \bigg]_{1}^{2} = \frac{5}{2}$$

The integration results are with possibility 0.4. Then,

$$\tilde{I}_{0.4}(1,2) = \{(\frac{3}{2}, 0.4), (\frac{5}{2}, 0.4)\}.$$

Finally, we have the total integration.

$$\tilde{I}(1,2) = \{(\frac{7}{3}, 0.7), (\frac{3}{2}, 0.4), (\frac{5}{2}, 0.4)\}$$

2.4.2 Integration of a (Crisp) Real Valued Function Over a Fuzzy Interval

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rmalized convex fuzzy sets. The membership function

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 \tilde{b} D. If a_0 and b_0 are the lower/upper limits of the supports of \tilde{a} or \tilde{b} , then

 a_0 or b_0 are related to each other by $\underline{a}_0 = \text{Inf } S(\tilde{a}) \leq \text{Sup } S(\tilde{b}) = b_0$.



Fig.(2.6) Fuzzily bounded interval.

Definition (2.4)[Klir, G. J., 2000]:

Let *f* be a real valued function which is integrable in the interval $J = [a_0, b_0]$, then according to the extension principle the membership function of the fuzzy integral $\int f$ is given by:

$$\mu_{\int_{\widetilde{D}}^{f}}(z) = \sup_{x, y \in J: z = \int_{f}^{y}} Min \{\mu_{\widetilde{a}}(x), \mu_{\widetilde{b}}(y)\}.$$

Some Properties of The Integration of Crisp Function over Fuzzy Interval

[Klir, G. J., 2000]:

1. Let f be any function $f: D \rightarrow R$, which is integrable on D, then:

$\int f = F(\tilde{b}) \Theta F(\tilde{a}).$

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where Θ denotes the extended subtrac

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where \subseteq denotes the usual fuzzy set inclusion ($\tilde{A} \subseteq \tilde{B} \Leftrightarrow \mu_{\tilde{A}} \leq \mu_{\tilde{B}}$) and \oplus denotes the extended addition.

3. If
$$f, g: I \longrightarrow R^+$$
 or $f, g: I \longrightarrow R^-$, then:

$$\int_{a}^{b} (f+g) = \int_{a}^{b} f \oplus \int_{a}^{b} g$$

The following examples illustrate fuzzy integration and its properties:

Example (2.9):

Let:

$$\tilde{a} = \{(4, 0.8), (5, 1), (6, 0.4)\}$$

$$\tilde{b} = \{(6, 0.7), (7, 1), (8, 0.2)\}$$

and, $f(x) = 2, x \in [a_0, b_0] = [4, 8]$

The problem is to find the fuzzy integration of f(x) over J = [4, 8]. The following table illustrate these results.

Table (2.1)

Integration of f(x)=2, over an interval (a,b) with membership function

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(4, 8)	8	0.2
(5, 6)	2	0.7
(5,7)	4	1.0
(5, 8)	6	0.2
(6, 6)	0	0.4
(6, 7)	2	0.4
(6, 8)	4	0.2

and by using the definition (2.4), then:

$$\int_{\tilde{D}} f = \{(0, 0.4), (4, 0.7), (4, 1), (6, 0.8), (8, 0.2)\}.$$

Example (2.10):

Let:

$$f(x) = 2x - 3, g(x) = -2x + 5$$

and

$$\widetilde{a} = \{(1, 0.8), (2, 1), (3, 0.4)\}\$$

 $\widetilde{b} = \{(3, 0.7), (4, 1), (5, 0.3)\}$

so:

$$\int_{a}^{b} f(x) dx = x^{2} - 3x |_{a}^{b} = (b^{2} - 3b) - (a^{2} - 3a).$$

 $\left[g(x) \, dx = -x^2 + 5x \right]_{a}^{b} = (-b^2 + 5b) - (-a^2 + 5a).$

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$$\int_{\tilde{a}}^{\tilde{a}} g = \{(-6, 0.3), (-4, 0.3), (-2, 1), (0, 0.8), (2, 0.7)\}$$

$$\int_{\tilde{a}}^{\tilde{b}} f \oplus \int_{\tilde{a}}^{\tilde{b}} g = \{(-6, 0.3), (-4, 0.3), (-2, 0.4), (0, 0.7), (2, 0.7), (4, 1), (6, 0.8), (8, 0.7), (10, 0.3), (12, 0.3), (14, 0.3)\}$$

$$\int_{\tilde{a}}^{\tilde{b}} (f + g) = \{(0, 0.4), (2, 0.7), (4, 1), (6, 0.8), (8, 0.3)\}$$

and it is clear that:

$$\int_{\tilde{a}}^{\tilde{b}} f \oplus \int_{\tilde{a}}^{\tilde{b}} g \supseteq \int_{\tilde{a}}^{\tilde{b}} f + \int_{\tilde{a}}^{\tilde{b}} g.$$

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Solution of fuzzy DIFFERENTIAL EQUATIONS

Fuzzy differential equations with initial or boundary conditions are of

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Benefits for registered users: uniqueness theorem of the providence of the

problem, and modifying the approach to solve the non-homogenous and

nonlinear fuzzy initial value problems.

Also, this chapter consists of an introduction to other types of fuzzy differential equations with boundary conditions which is solved by using the shooting method to solve numerically boundary value problems.

3.1 FUZZY DIFFERENTIAL EQUATIONS

Most dynamical real life problems could be formulated as a mathematical model, in which most of them are formulated either as system of ordinary or partial differential equations, especially in mathematical physics. Therefore, studies could be oriented toward two directions. The first direction is the evaluation of the solution and modifying methods to find such

solution. While the second orientation is to study the stability of solutions without evaluating this solution explicitly.

In connection with these studies of differential equations a new field appeared recently in the late of 20-th century, which is the so called *fuzzy differential equations*.

Consider the fuzzy differential equations:

 $y'(t) = f(t, y), \ y(t_0) \square \ \tilde{y}_0, \forall t \in D$(3.1)

Where t_0 , \tilde{y}_0 are given, It's clear that the solution will depend on the fuzzy initial and hence the solution y(t) will be fuzzy and also f is a given function.

Before studying the solution of fuzzy differential equations, we will first study the existence and uniqueness theorem of fuzzy differential equations.

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 $T(\tilde{A}) = \sup \left\{ \mu_{\tilde{A}}(w) | w \in T^{-1}(x) \right\}$

where \tilde{A} is a fuzzy set and T(w) = x. If X^* and Y^* are fuzzy Banach spaces, then *T* is called *fuzzy operator*.

Also, if $T(c_1\tilde{A} + c_2\tilde{B}) = c_1T(\tilde{A}) + c_2T(\tilde{B})$, $\forall \tilde{A}, \tilde{B} \in I^X$ and $c_1, c_2 \in R$ or C, then \tilde{T} is called *linear operator*.

Definition (3.2)[Najeib S.W., 2002]:

A fuzzy function $\tilde{F}: X \to F(R)$ is called levelwise continuous at $t_0 \in X$ if the mapping F_{α} is continuous at $t = t_0$ with respect to the Hausdorff metric D_H on F(R) for all $\alpha \in [0,1]$.

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3.2 THE EXISTENCE AND UNIQUNESS THEOREM OF FUZZY DIFFERENTIAL EQUATIONS USING SCHAUDER FUZZY FIXED POINT THEOREM

In this section, the existence and uniqueness theorem of fuzzy differential equations is considered using Schauder fuzzy fixed point theorem. The proof of the theorem is given by transforming the fuzzy differential equation to an alternative Volterra fuzzy integral equation and then satisfying the conditions of the Schauder fuzzy fixed point theorem.

First, recall the fuzzy version of Schauder fixed point.

Theorem (3.1) (Schauder Fuzzy Fixed Point Theorem) [Al-Hamaiwand S.M., 2001]:

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existence of the solution of the fuzzy initial value problems by proving the existence of a solution of the fuzzy integral equation. This is important, because integrals are in general easier to estimate than derivatives, also integral equations could carry iterations rather than differentiation.

Definition(3.3) [Park and Han, 1999]:

A mapping $y: I \longrightarrow E^n$ is a solution to the problem y'(t) = f(t, y(t)),

 $y(t_0) \square \tilde{y}_0$, if it is levelwise continuous and satisfy the integral equation:

Definition (3.4) [Park and Han, 1999]:

A function $[f]^{\alpha}$ which satisfies an inequality of the form

for all (t, x_1) , (t, x_2) in a region D is said to satisfy a Lipschitz condition to

 $[f]^{\alpha}$ on D, where d represent the Hausdorff distance

Remark (3.1) [Park and Han, 1999]:

Define δ to be the smaller of the two positive numbers of a and $\frac{b}{M}$,

then the fuzzy integral equation (3.2) is defined on the interval

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 $I_{\delta} = \left\{ t : |t - t_0| \le \delta \right\}$

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and suppose \tilde{A} be an open fuzzy subset of $D \equiv R \times C[R^+ \times S(\alpha), R^n]$, where

 $S(\alpha) = \{ \mu \in \mathbb{R}^n : d^*(\tilde{y}, \tilde{y}_0) < \alpha \}$ and $f : \tilde{A} \to \mathbb{R}^n$ be levelwise continuous and bounded function for any $(t_0, y(t)) \in \tilde{A}$, then there exist a solution to (3.5) which passes through (t_0, y) .

Proof:

The proof is based on Schauder fuzzy fixed point theorem (3.1). First of all, in order to fix our symbols, define the following sets:

 $I_T = \{t \in R : 0 \le t \le T\} \text{ and } B_\beta = \{\tilde{\psi} \in C : \|\tilde{\psi}\| \le 1 + \beta\}.$

and suppose that f is bounded function at t_0 , that is, there exist $M \in R^+$, such that:

 $||f(t_0, y)|| \le M$ (3.6)

Since f is levelwise continues, then there exist $\delta, \beta > 0$, such that:

$$\|f(t_0+t, y+\tilde{\psi})\| \le M$$
, where $(t,\tilde{\psi}) \in I_T \times B_\beta$ (3.7)

Now, since our proof depends on the Schauder fuzzy fixed point theorem, then it sufficient to prove that I^X is a non empty, closed, bounded, and convex fuzzy subset of a fuzzy Banach space *B* and then the fuzzy operator $\tilde{T}: I^X \to I^X$ is a compact fuzzy operator.

Another set which will be constructed that contains all fuzzy subsets, such that, for any $\alpha^*, \beta^* \in R$ let:

$$A(\alpha^*,\beta^*) = \left\{ \tilde{\zeta}(t) \in C[R^+ \times S(\alpha^*),R^n]; \tilde{\zeta}(0) \square 0, \tilde{\zeta}(t) \in B_{\beta^*}, t \in I_{\alpha^*} \right\}$$

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Hence

$$\left\| \tilde{\zeta}(t) + \tilde{\varphi}(t_0 + t) - \tilde{\varphi}(t) \right\| \le \left\| \tilde{\zeta}(t) \right\| + \left\| \tilde{\varphi}(t_0 + t) - \tilde{\varphi}(t) \right\|$$
$$\le \beta^* + \beta - \beta^* = \beta < 1 + \beta$$

Now, using (3.7) we have

$$\left\|f\left(t_0+t,\tilde{\zeta}(t)+\tilde{\varphi}(t_0+t)\right)\right\| \leq M, t \in I_{\alpha^*}, \tilde{\zeta} \in A(\alpha^*,\beta^*).$$

Now, we will define a fuzzy operator \tilde{T} , as follows:

$$\tilde{T}: A(\alpha^*, \beta^*) \to C[R^+ \times S(\alpha), R^n] \subseteq A(\alpha^*, \beta^*).$$

and

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$$\tilde{T}(\tilde{\zeta}(t)) = \begin{cases} \tilde{y}_0 + \int_0^t f(s, \tilde{\zeta}(s))ds & , \text{if } t \in I_{\alpha^*} \\ 0 & , \text{if } t = 0 \end{cases}$$

Since the fuzzy fixed points of \tilde{T} in $A(\alpha^*, \beta^*)$ is a solution to the fuzzy differential equation with the following constraint:

 $y(t_0+t) = \tilde{\zeta}(t) + \tilde{\varphi}(t_0+t).$

Now, to prove that $A(\alpha^*, \beta^*)$ is a closed, bounded and convex fuzzy subset of $C[R^+ \times S(\alpha^*), R^n]$.

It is clear that $A(\alpha^*, \beta^*)$ is closed and bounded fuzzy set (by construction).

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To prove

$$\tilde{\zeta}^*(t) = \lambda \tilde{\zeta}_1(t) + (1 - \lambda) \tilde{\zeta}_2(t) \in A(\alpha^*, \beta^*).$$

i.e., to prove $\tilde{\zeta}^*(t) \in C[R^+ \times S(\alpha^*), R^n], \ \tilde{\zeta}^*(0) \square 0, \ \tilde{\zeta}^*(t) \in B_{\beta^*}.$

Now, since $\tilde{\zeta}_1(t), \tilde{\zeta}_2(t) \in C[R^+ \times S(\alpha^*), R^n]$ and since the linear combination of levelwise continuous functions are also levelwise continuous, hence:

$$\tilde{\zeta}^*(t) \in C[R^+ \times S(\alpha^*), R^n].$$

and also

$$\begin{split} \tilde{\zeta}^*(0) &= \lambda \tilde{\zeta}_1(0) + (1 - \lambda) \tilde{\zeta}_2(0) \\ &= \lambda . 0 + (1 - \lambda) . 0 = 0 \,. \end{split}$$

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Moreover, to prove that $\|\tilde{\zeta}^*(t)\| \in A(\alpha^*, \beta^*)$ i.e., to prove $\|\tilde{\zeta}^*(t)\| \le 1 + \beta^*$

$$\begin{split} \left\| \tilde{\zeta}^{*}(t) \right\| &= \left\| \lambda \tilde{\zeta}_{1}(t) + (1 - \lambda) \tilde{\zeta}_{2}(t) \right\| \\ &\leq \left\| \lambda \tilde{\zeta}_{1}(t) \right\| + \left\| (1 - \lambda) \tilde{\zeta}_{2}(t) \right\| = \left| \lambda \right| \left\| \tilde{\zeta}_{1}(t) \right\| + \left| 1 - \lambda \right| \left\| \tilde{\zeta}_{2}(t) \right\| \\ &\leq \lambda \beta^{*} + (1 - \lambda) \beta^{*} = \beta^{*} < 1 + \beta^{*}. \end{split}$$

So, $\tilde{\zeta}^{*}(t) = \lambda \tilde{\zeta}_{1}(t) + (1 - \lambda) \tilde{\zeta}_{2}(t) \in A(\alpha^{*}, \beta^{*})$

Hence, $A(\alpha^*, \beta^*)$ is a convex set.

Now, since the composition of two levelwise continuous functions is levelwise continuous, hence $\tilde{T}(\tilde{\zeta}(t))$ is also levelwise continuous and since $\tilde{T}(\tilde{\zeta}(0)) \Box 0$ then $\tilde{T}(\tilde{\zeta}(t)) \in C[R^+ \times S(\alpha^*), R^n]$.

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$$\leq 1 + \int_{0}^{t} \left\| f(s, \tilde{\zeta}(s)) \right\| ds$$

$$\leq 1 + Mt$$

$$\leq 1 + M\alpha^{*} \leq 1 + \beta^{*}$$

Hence, $\tilde{T}(\tilde{\zeta}(t)) \in B_{\beta^*}$, i.e., $\tilde{T}(\tilde{\zeta}(t)) \in A(\alpha^*, \beta^*)$.

Now, to prove \tilde{T} is levelwise continuous on $A(\alpha^*, \beta^*)$.

Let $t, t_1 \in I_{\alpha^*}$ such that $|t - t_1| < \delta$, then:

$$\left\|\tilde{T}(\tilde{\zeta}(t)) - \tilde{T}(\tilde{\zeta}(t_{1}))\right\| = \left\|\tilde{y}_{0}(t) + \int_{0}^{t} f \, ds - \tilde{y}_{0} - \int_{0}^{t_{1}} f \, ds\right\|$$

$$= \left\| \int_{t_1}^0 f \, ds + \int_0^t f \, ds \right\|$$
$$= \left\| \int_{t_1}^t f \, ds \right\| \le \int_{t_1}^t \left\| f \right\| \, ds \le \int_{t_1}^t M \, ds$$
$$= M \left(t - t_1 \right) \le M \left| t - t_1 \right| \le \varepsilon$$

If $|t-t_1| < \frac{\varepsilon}{M} = \delta(\varepsilon)$.

Hence, $\tilde{T}(A(\alpha^*, \beta^*))$ is contained in a compact subset of $C[R^+ \times S(\alpha^*), R^n]$. Now, let $\left\{ \tilde{\zeta}_k \right\}$ be a sequence in $A(\alpha^*, \beta^*)$ such that $\left\{ \tilde{\zeta}_k \right\} \rightarrow \tilde{\zeta}$, since f is

levelwise continuous on a compact set, then f is uniformly continuous on a

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i.e., T is a pointwise convergent in $A(\alpha, \beta)$.

i.e., \tilde{T} is levelwise continuous and maps compactly, the closed bounded and convex subset of $A(\alpha^*, \beta^*)$ into a subset of it, i.e., $\tilde{T}: A(\alpha^*, \beta^*) \to A(\alpha^*, \beta^*)$ is compact

Hence using Schauder fuzzy fixed point theorem, \tilde{T} has a fixed point which shows that the fuzzy fixed point x^* is the desired solution of the fuzzy differential equation.

Under the same conditions of the last theorem additional considerations are given in order to guarantee the uniqueness of the solutions as it is seen in the next theorem:

Theorem (3.3) (The Uniqueness Theorem):

Let \tilde{A} be an open fuzzy subset of $R \times C[R^+ \times S(\alpha^*), R^n]$ and suppose that $f : \tilde{A} \to R^n$ be levelwise continuous and $f(t, \tilde{\varphi})$ be Lipschitzian with respect to $\tilde{\varphi}$ in every compact fuzzy subset of \tilde{A} with Lipschitz constant K. If $(x_0, \tilde{\varphi}) \in \tilde{A}$, then the fuzzy differential equation (3.1) has a unique solution passes through $(x_0, \tilde{\varphi})$ where $KT^* < 1$.

Proof:

Consider I_T and B_β which are defined as in theorem (3.1), and let x(t), y(t) be any two functions related to the solution of the fuzzy differential equation on $[R^+ \times S(\alpha^*), R^n]$ with $x(x_0) = \tilde{\varphi}(t) = y(x_0)$, hence:

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$$\leq \int_{t_0}^{t} K \|x(s) - y(s)\| ds$$

$$\leq KT^* \sup_{x_0 \le s \le 1} \|x(s) - y(s)\| < \sup_{x_0 \le s \le 1} \|x(s) - y(s)\| < \varepsilon$$

We can choose T^* small as necessary to insure that $K\alpha^* < 1$, for all $t \in I_{\alpha^*}$. Hence $x(t) = y(t), \forall t \in I_{\alpha^*}$.

This completes the proof of the theorem.

3.3 SOLUTION OF LINEAR HOMOGENOUS FUZZY SYSTEM [PEARSON D.W., 1997]

Consider the following fuzzy differential equation

 $x' = f(x), x(0) \square \tilde{x}_0$

where the structure of the equation is known, represented by a given vector field *f*, but the model parameters on the initial value \tilde{x}_0 are not known exactly and the initial condition is a fuzzy number.

3.3.1 Solution of Fuzzy Differential Equations [Pearson D.W., 1997]:

In this subsection, we shall study, as a survey, a method for solving linear system of fuzzy differential equations.

Consider the problem of solving the fuzzy linear homogenous

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A fuzzy number \tilde{x}_0 , can be prescribed easily by its α -level sets, as:

 $[x_0]_{\alpha} = \{s : \tilde{x}_0 \ (s) \ge \alpha\}, 0 \le \alpha \le 1.$

Due to the properties of the so defined fuzzy numbers, corresponds to an interval for each given value of α :

 $[x_0]_{\alpha} = [\underline{x}_0, \overline{x}_0]$

where \underline{x}_0 and \overline{x}_0 represents the lower and upper bounds of the fuzzy number \tilde{x}_0 .

Suppose that each element of the vector x in (3.9) at time t is a fuzzy number, where:

$$x^{k}(t) = [\underline{x}_{\alpha}^{k}(t), \, \overline{x}_{\alpha}^{k}(t)], \, k = 1, 2, \dots, n \dots (3.10)$$

it is shown that the evolution of the system (3.9) can be described by 2ndifferential equations for the end points of the intervals, this is for each given time instant t and value of α . These equations for the end points of the intervals are:

$$\frac{\dot{x}_{\alpha}^{k}(t) = \operatorname{Min}\{\sum_{j=1}^{n} a_{kj}u^{j} : u^{i} \in [\underline{x}_{\alpha}^{i}(t), \overline{x}_{\alpha}^{i}(t)]\}}{\dot{\overline{x}}_{\alpha}^{k}(t) = \operatorname{Max}\{\sum_{j=1}^{n} a_{kj}u^{j} : u^{i} \in [\underline{x}_{\alpha}^{i}(t), \overline{x}_{\alpha}^{i}(t)]\}} \right\} \dots (3.11)$$

with initial conditions $\underline{x}_{\alpha}^{k}(0) = \underline{x}_{\alpha 0}^{k}, \ \overline{x}_{\alpha}^{k}(0) = \overline{x}_{\alpha 0}^{k}$

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$$u^{j} = \begin{cases} \frac{\underline{x}_{\alpha}^{j}(t), & \text{if } a_{kj} \ge 0\\ \overline{x}_{\alpha}^{j}(t), & \text{if } a_{kj} < 0 \end{cases}$$

and

$$\vec{x}_{\alpha}^{\prime k}(t) = \sum_{j=1}^{n} a_{kj} u^{j} \qquad (3.13)$$

where:

$$u^{j} = \begin{cases} \overline{x}_{\alpha}^{j}(t), & \text{if } a_{kj} \ge 0\\ \\ \underline{x}_{\alpha}^{j}(t), & \text{if } a_{kj} < 0 \end{cases}$$

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This means, for example, for any $\alpha \in [0,1]$ and k = 1, 2, 3, (i.e., 3×3 system), then six differential equations will be obtained where two of them are for each *k* and each α related to one of end points, in other words:

$$x_{\alpha}^{k}(t) = \left[\underline{x}_{\alpha}^{k}(t), \ \overline{x}_{\alpha}^{k}(t)\right] = \begin{bmatrix} \underline{x}_{\alpha}^{1}(t) & \overline{x}_{\alpha}^{1}(t) \\ \underline{x}_{\alpha}^{2}(t) & \overline{x}_{\alpha}^{2}(t) \\ \underline{x}_{\alpha}^{3}(t) & \overline{x}_{\alpha}^{3}(t) \end{bmatrix}$$

The method for solving directly linear fuzzy system is meaningless; therefore an introduction of the representation of the fuzzy system using complex numbers is necessary

In order to solve the fuzzy system of differential equations:

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and the two operations carried on the complex numbers as:

(a) Identity operation which is given by e, such that:

(b) The operator g corresponding to a flip about the diagonal in the complex plane, i.e.

where $g^2 = e$ and $g^k = e$ if k is even and $g^k = g$ if k is odd, and therefore:
Using (3.14), (3.15) and (3.16), yields:

$$z^k_\alpha = \underline{x}^k_\alpha(t) \, + i \ \overline{x}^k_\alpha(t)$$

and hence:

$$z_{\alpha}^{\prime k} = \underline{x}_{\alpha}^{\prime k}(t) + i \, \overline{x}_{\alpha}^{\prime k}(t)$$

but $\underline{x}'_{\alpha}^{k}(t) = \sum_{j=1}^{n} a_{kj} u^{j}$ and $i \ \overline{x}'_{\alpha}^{k}(t) = i \ \sum_{j=1}^{n} a_{kj} u^{j}$. Then:

$$\underline{x}_{\alpha}^{\prime k}(t) + i \, \overline{x}_{\alpha}^{\prime k}(t) = \sum_{j=1}^{n} a_{kj} u^{j} + i \sum_{j=1}^{n} a_{kj} u^{j}$$

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$$= \begin{cases} a_{kj} z_{\alpha}^{k}, & \text{if } a_{kj} \ge 0\\ a_{kj} (g z_{\alpha}^{k}), & \text{if } a_{kj} < 0 \end{cases}$$

Now, using equation (3.17), whenever:

$$z_{\alpha}^{\prime k} = \begin{cases} a_{kj} z_{\alpha}^{k}, & \text{if } a_{kj} \ge 0\\ g a_{kj} z_{\alpha}^{k}, & \text{if } a_{kj} < 0 \end{cases}$$

and in order to simplify the last formula, let:

$$b_{ij} = \begin{cases} ea_{ij}, & if \quad a_{ij} \ge 0\\ ga_{ij}, & if \quad a_{ij} < 0 \end{cases}$$
(3.18)

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then:

$$z_{\alpha}^{\prime k} = \begin{cases} b_{ij} z_{\alpha}^{k}, & \text{if } a_{kj} \ge 0\\ b_{ij} z_{\alpha}^{k}, & \text{if } a_{kj} < 0 \end{cases}$$

or in matrix form:

$$z_{\alpha}^{\prime k} = B z_{\alpha}^{k}$$

with initial condition $z_{\alpha}(0) = z_{\alpha 0}$.

Now, x' = Ax, which has the solution $x = ce^{At}$ and since $x(0) = x_0$, then $x(t) = x_0 e^{At}$. Similarly:

 $z_{c}(t) = z_{c0} e^{Bt}$ (3.19)

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B = eC + gD

and for small *t*, we have:

$$\exp(tB)z_{\alpha 0} = \exp(t(eC + gD))z_{\alpha 0}$$

$$= \exp(teC) \exp(tgD) z_{\alpha 0} + O(t)$$

where O(t) is a function of t, such that O(t)/t = 0 as $t \longrightarrow 0$. The first part $\exp(teC)$ is simply the standard matrix exponential, because e is the identity operator. For the second part $\exp(tgD)$, noting that $g^k = e$ if k is even and $g^k = g$ if it is odd and then proceed to calculate the formal power series of $\exp(tgD)$ as follows:

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$$\exp(tgD)z_{0} = \left(I + tgD + \frac{t^{2}}{2!}g^{2}D^{2} + \frac{t^{3}}{3!}g^{3}D^{3} + \dots\right)z_{0}$$
$$= \left(I + \frac{t^{2}}{2!}g^{2}D^{2} + \dots\right)z_{0} + \left(tgD + \frac{t^{3}}{3!}g^{3}D^{3} + \dots\right)z_{0}$$
$$= \left(I + \frac{t^{2}}{2!}D^{2} + \dots\right)z_{0} + \left(tD + \frac{t^{3}}{3!}D^{3} + \dots\right)gz_{0}$$

 $=\cosh(tD)z_0+\sinh(tD)gz_0$

Hence:

 $z_{\alpha 0}(t) = \exp(tC)(\cosh(tD)z_{\alpha 0} + \sinh(tD)gz_{\alpha 0})$

Let $\varphi(t) = \exp(tC)\cosh(tD)$ and $\psi(t) = \exp(tC)\sinh(tD)$. Then:

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 $= \varphi_{kj}(t)(\underline{x}_{\alpha 0}^{j}(t) + i \overline{x}_{\alpha 0}^{j}(t)) + \psi_{kj}(t)(\overline{x}_{\alpha 0}^{j}(t) + i \underline{x}_{\alpha 0}^{j}(t))$

Therefore:

$$\underline{x}_{\alpha}^{k}(t) = \sum_{j=1}^{n} \varphi_{kj}(t) \underline{x}_{\alpha_{0}}^{j}(t) + \psi_{kj}(t) \overline{x}_{\alpha_{0}}^{j}(t)$$
$$\overline{x}_{\alpha}^{k}(t) = \sum_{j=1}^{n} \varphi_{kj}(t) \overline{x}_{\alpha_{0}}^{j}(t) + \psi_{kj}(t) \underline{x}_{\alpha_{0}}^{j}(t)$$

.....(3.20)

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Example(3.1) [Pearson D.W., 1997]:

Consider the linear system x' = Ax, where $A = \begin{bmatrix} -1 & 1 \\ 0 & -2 \end{bmatrix}$ with initial

values to be $x_1(0)$ about 1 and $x_2(0)$ about -1, which are fuzzy numbers and using the membership functions defined by setting, for example,

$$x_0^1(s) = \begin{cases} 0, & s < 0\\ 2s - s^2, & 0 \le s < 2\\ 0, & s > 2 \end{cases}$$

and



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Thus, for $\alpha \in [0, 1]$, we can represent the initial condition

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The approximate solution given by equation (3.20), which takes the form:

$$\underline{x}_{\alpha}^{k}(t) = \sum_{j=1}^{n} \varphi_{kj}(t) \underline{x}_{\alpha_{0}}^{j}(t) + \Psi_{kj}(t) \overline{x}_{\alpha_{0}}^{j}(t)$$
$$\overline{x}_{\alpha}^{k}(t) = \sum_{j=1}^{n} \varphi_{kj}(t) \overline{x}_{\alpha_{0}}^{j}(t) + \Psi_{kj}(t) \underline{x}_{\alpha_{0}}^{j}(t)$$

So, if we let for simplicity

$$a = 1 - \sqrt{1-\alpha}$$
, $b = 1 + \sqrt{1-\alpha}$, $c = -1 - \sqrt{1-\alpha}$, $d = -1 + \sqrt{1-\alpha}$

Then the approximate solution could be evaluated as follows:

To find *B*, recall that $b_{ii} = ea_{ii}$ if $a_{ii} \ge 0$ and $b_{ii} = ga_{ii}$ if $a_{ii} < 0$, then

 $a_{11} = -1$ implies that $b_{11} = g(-1) = -i$, $a_{12} = 1 \ge 0$ implies $b_{12} = e(1) = 1$ and so on. $B = \begin{bmatrix} ga_{11} & ea_{12} \\ ea_{21} & ga_{22} \end{bmatrix} = \begin{bmatrix} -i & 1 \\ 0 & -2i \end{bmatrix}$ and we can write the matrix *B* as the sum

of two matrices, the first matrix is multiplied by the operator e and the other is multiplied by g, hence:

$$B = \begin{bmatrix} -i & 1 \\ 0 & -2i \end{bmatrix}$$
$$= \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix}$$
$$= c \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix} = cC + cC$$

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Therefore:

$$p(t) = e^{Ct} \cosh(tD)$$

$$= \begin{bmatrix} 1 + \frac{t^2}{2!} + \frac{t^4}{4!} + \dots & t + 2t^3 + \frac{2}{3}t^5 + \dots \\ 0 & 1 + 2t^2 + \frac{2}{3}t^4 + \dots \end{bmatrix}$$

Similarly, one can find sinh(tD), which takes the form:

Sinh(*tD*) =
$$\begin{bmatrix} -t - \frac{t^3}{3!} - \dots & 0\\ 0 & -2t - \frac{4}{3}t^3 - \dots \end{bmatrix}$$

Hence:

$$\psi(t) = e^{Ct} \sinh(tD)$$
$$= \begin{bmatrix} -t - \frac{t^3}{3!} - \dots & -2t^2 - \frac{4}{3}t^4 - \dots \\ 0 & -2t - \frac{4}{3}t^3 - \dots \end{bmatrix}$$

Now, letting t = 0.2, we have:

$$\varphi(0.2) = \begin{bmatrix} 1.020066 & 0.216213 \\ 0 & 1.08166 \end{bmatrix}$$
$$\psi(0.2) = \begin{bmatrix} -0.201333 & -0.082133 \\ 0 & -0.410606 \end{bmatrix}$$

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 $\overline{x}_{\alpha}^{2}(0.2) = -0.41066666c + 1.080666d$

For example, if $\alpha = 0.1$, then

$$\underline{x}_{0.1}^{1}(0.2) = -0.7570682, \ \overline{x}_{0.1}^{1}(0.2) = 2.126394$$

$$\underline{x}_{0.1}^2(0.2) = -2.085526$$
 and $\overline{x}_{0.1}^2(0.2) = 0.744773$

and so on for any value of $\alpha \in [0,1]$.

Remarks(3.2):

1- In order to check the accuracy of the results, a comparison have been made between the crisp solution and the approximate solution of a fuzzy

system at $\alpha = 1$, in which this comparison will be given in the following graph:



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Fig (3.2) Compare between the second solution of the system (the crisp solution and the fuzzy solution with α =1).

2- The next two figures presents the membership functions for the solutions x^1 and x^2 at t = 0.2 for each $0 \le \alpha \le 1$ with step size 0.1.



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Fig (3.4) represents the upper and lower solutions of x^2 at t = 0.2 at each $0 \le \alpha \le 1$ with step size 0.1.

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3.4 SOLUTION OF NON-HOMOGENOUS AND NONLINEAR SYSTEM OF FUZZY DIFFERENTIAL EQUATIONS

The last approach followed in section (3.3) is so difficult to modify for solving non-homogenous fuzzy systems.

Therefore, new approaches are given in this section for solving nonhomogenous fuzzy differential equations. The approximate methods followed in this section are:

- 1- The method of successive approximation for solving nonhomogenous fuzzy systems.
- 2- The method of linearization for solving nonlinear and nonhomogenous fuzzy systems.

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function \tilde{f} , the initial condition \tilde{y}_0 and the solution $\tilde{y}(t)$ are assumed to be fuzzy while the parameter t is considered to be crisp. where h(t) represent the non-homogenous term.

Now, according to definition (3.3), then equation (3.21) is equivalent to the fuzzy integral equation (3.2). The problem now is to solve the fuzzy integral equation (3.2), and recalling the solution of this problem had been discussed by [Najieb S.W., 2002].

Now, the method of successive approximations for solving fuzzy integral equations is to consider the fuzzy integral equation:

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$$\tilde{y}(t) = \tilde{y}_0 + \int_0^t \left[\tilde{K}(t,x)\tilde{y}(x) + \tilde{h}(x) \right] dx$$
(3.22)

where $\tilde{y}(t) = ((y_i(t), \alpha_i)), \quad \tilde{K}(t, x) = ((K_i(t, x), \alpha_i)), i=1,2,...,n.$ Then:

$$\left((y_i(t),\alpha_i)\right) = \left(\tilde{y}_0\right) + \int_o^t \left((K_i(t,x),\alpha_i)\right) \left((y_i(x),\alpha_i)\right) + \left((h_i(x),\alpha_i)\right) dx$$

Implies

Which implies that $\forall \alpha_i \in [0,1]$.

 $y_i(t) = y_0 + \int [K_i(t, x)y_i(x) + h_i(x)]dx, \quad \forall i = 1, 2, ..., n \quad \quad (3.24)$

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and for each $\alpha_i \in [0,1]$

Example(3.2)

To solve the non-homogenous fuzzy differential equation

$$\tilde{y}' = \tilde{f}(t, \tilde{y}) = \tilde{k}(t, x)\tilde{y}(t) + \tilde{h}(t)$$
 where

$$\widetilde{k}(t, x) = \{(k_1(t, x), 0.4), (k_2(t, x), 1.0)\}$$

$$\widetilde{h}(t) = \{(h_1(t), 0.4), (h_2(t), 1.0)\}$$

and, $k_1(t, x) = \frac{1}{2}t$, $k_2(t, x) = 1$, $h_1(t) = \frac{1}{2}t$ and $h_2(t) = 1$.

Applying equation (3.25), we get for $\alpha = 0.4$

$$\tilde{y}_{1}^{(m+1)}(t) \square \tilde{y}_{0} + \int_{0}^{t} \left[\tilde{K}_{1}(t,x) \tilde{y}_{1}^{(m)}(x) + h_{1}(x) \right] dx$$

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Since, $y_1^{(0)}(t) = 1$ then from equation (3.25) we obtain:

$$y_1^{(1)}(t) = 1 + \int_0^t \left[\frac{1}{2}x + \frac{1}{2}x\right] dx = 1 + \frac{t^2}{2}$$

and hence:

$$y_{1}^{(2)}(t) = 1 + \int_{0}^{t} \left[\frac{1}{2}x(1 + \frac{t^{2}}{2}) + \frac{1}{2}x\right] dx = 1 + \frac{t^{2}}{2} + \frac{t^{4}}{4}$$

$$y_{1}^{(3)}(t) = 1 + \int_{0}^{t} \left[\frac{1}{2}x(1 + \frac{t^{2}}{2} + \frac{t^{4}}{4}) + \frac{1}{2}x\right] dx = 1 + \frac{t^{2}}{2} + \frac{t^{4}}{8} + \frac{t^{6}}{16}$$

$$y_{1}^{(4)}(t) = 1 + \int_{0}^{t} \left[\frac{1}{2}x(1 + \frac{t^{2}}{2} + \frac{t^{4}}{4}) + \frac{t^{6}}{16} + \frac{t^{6}}{16}$$

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Now, for $\alpha = 1$, we have

$$\tilde{y}_{2}^{(m+1)}(t) \Box \tilde{y}_{0} + \int_{0}^{t} \left[\tilde{K}_{2}(t,x) \tilde{y}_{2}^{(m)}(x) + h_{2}(x) \right] dx$$
$$\tilde{y}_{2}^{(m+1)}(t) \Box 1 + \int_{0}^{t} \left[1. \tilde{y}_{2}^{(m)}(x) + 1 \right] dx$$

and similarly:

$$\tilde{y}_{2}^{(1)}(t) \Box 1 + \int_{0}^{t} [(1).(1) + 1] dx = 1 + 2t.$$

$$\tilde{y}_{2}^{(2)}(t) \Box 1 + \int_{0}^{t} [(1).(1 + 2t) + 1] dx = 1 + 2t + t^{2}$$

$$\tilde{y}_{2}^{(3)}(t) \Box 1 + \int_{0}^{t} \left[(1) \cdot (1 + 2t + t^{2}) + 1 \right] dx = 1 + 2t + t^{2} + \frac{t^{3}}{3}.$$

if we continue in this process we get $y_2(t)$ also as

$$y_2(t) = 1 + 2t + t^2 + \frac{t^3}{3} + \dots$$

$$=1+2(e^t-1)$$

So the solution of the fuzzy integral equation (which is equivalent to the solution of the fuzzy differential equation) is given by:

 $\widetilde{y}(t) = \{(\cosh(t), 0.4), (1+2(e^t - 1), 1.0)\}.$

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3.4.2 Linearization Technique for Solving Linearization Technique for Solving Linearization Technique for Solving Linearization Solving Linearizatio Solving Linearization Solving Linearization Solving Linearizat

problems.

The solution of fuzzy differential equations in this subsection deals with ordinary differential equations with fuzzy initial values.

The linearization approach depends on transforming the non-linear fuzzy system to a linear fuzzy system and then using the method of parametric equations (see section 3.3) to solve the resulting system.

Similar approach can be used to solve non-homogenous system of fuzzy differential equations.

The solution of fuzzy differential equations are also compared with the exact solution of ordinary differential equations, i.e., with crisp initial values when $\alpha = 1$.

3.4.2.1 Linearization Theorem of Non-Linear and Non-Homogenous Fuzzy Differential Equations

Suppose that the non-linear fuzzy system given by:

 $y' = f(x, y), \ y(x_0) \square \ \tilde{y}_0$

where *f* is a given function which is assumed to be differentiable, x_0 is fixed and \tilde{y}_0 is given fuzzy number which can be rewritten as:

 $y' \Box Ay + g(y), y(x_0) \Box \tilde{y}_0$ (3.27)

or

$$y'_{1} = a_{11}y_{1} + a_{12}y_{2} + \dots + a_{1n}y_{n} + g_{1}(y_{1}, y_{2}, \dots, y_{n})$$

$$y'_{2} = a_{21}y_{1} + a_{22}y_{2} + \dots + a_{2n}y_{n} + g_{2}(y_{1}, y_{2}, \dots, y_{n})$$

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is said to be the linearization (or the linearized system) of (3.27) at the

equilibrium point.

The systematic approach of obtaining the linearization is by utilizing Taylor series expansion of a function $f(x_1, x_2, ..., x_n)$ in some neighborhood of a point $(\eta_1, \eta_2, ..., \eta_n)$ is given by:

$$f(x_1, x_2, ..., x_n) = f(\eta_1, \eta_2, ..., \eta_n) + (x_1 - \eta_1) \frac{\partial f}{\partial x_1}(\eta_1, \eta_2, ..., \eta_n) + (x_2 - \eta_2) \frac{\partial f}{\partial x_2}(\eta_1, \eta_2, ..., \eta_n) + ... + (x_n - \eta_n) \frac{\partial f}{\partial x_n}(\eta_1, \eta_2, ..., \eta_n) + r(x_1, x_2, ..., x_n).$$

where r is the reminder function satisfying

$$\lim_{r \to 0} \frac{r(x_1, x_2, ..., x_n)}{\Box} = 0$$

where $\Box = \sqrt{(x_1 - \eta_1)^2 + (x_2 - \eta_2)^2 + ... + (x_n - \eta_n)^2}$

therefore, if $(\eta_1, \eta_2, ..., \eta_n)$ is a fixed points of the system $y' = f(x_1, x_2, ..., x_n)$, then the linearized system is given by Y' = AY, where

$$A = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \dots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \dots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \frac{\partial f_n}{\partial x_2} & \dots & \frac{\partial f_n}{\partial x_n} \end{bmatrix}_{(x_1, x_2, \dots, x_n) = (\eta_1, \eta_2, \dots, \eta_n)}$$

The following examples illustrate the above discussion.

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Aence, the Jacobian at the critical point (-1,1):

$$J = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

Therefore, the linearized fuzzy system is given by:

$$y' = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}, \qquad y_1(0) \square \tilde{1}, \quad y_2(0) \square -\tilde{1}.$$

Now, using the method discussed in section (3.3), to solve the linear homogenous fuzzy system

$$B = \begin{bmatrix} 1 & 0 \\ 0 & -i \end{bmatrix}$$

$$= e \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + g \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix} = eC + gD$$

Hence,

$$e^{Ct} = \begin{bmatrix} e^t & 0\\ 0 & 1 \end{bmatrix}$$
 and $\cosh(tD) = \begin{bmatrix} 1 & 0\\ 0 & \cosh(t) \end{bmatrix}$

Therefore:

$$\varphi(t) = e^{Ct} \cosh(tD) = \begin{bmatrix} e^t & 0\\ 0 & \cosh(t) \end{bmatrix}$$

Similarly:

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Now, letting t = 0.2, we have:

$$\varphi(0.2) = \begin{bmatrix} 1.02 & 0 \\ 0 & 1.02 \end{bmatrix}$$
 and $\psi(0.2) = \begin{bmatrix} 0 & 0 \\ 0 & -0.2 \end{bmatrix}$

and therefore the approximate solution is given by:

$$\underline{y}_{\alpha}^{1}(0.2) = (1.22)a , \ \overline{y}_{\alpha}^{1}(0.2) = (1.22)b , \ \underline{y}_{\alpha}^{2}(0.2) = (1.02)c + (-0.2)d$$

and $\overline{y}_{\alpha}^{2}(0.2) = (-0.2)c + (1.02)d$

where $a = 1 - \sqrt{1 - \alpha}$, $b = 1 + \sqrt{1 - \alpha}$, $c = -1 - \sqrt{1 - \alpha}$, $d = -1 + \sqrt{1 - \alpha}$.

<u>Remark(3.3)</u>

Now, To check the accuracy of the solution of the non-linear fuzzy system. We must find the solution of the non-linear crisp system by letting $\alpha = 1$. Letting $\alpha = 1$ gives $\underline{y}_1^1(t) = \overline{y}_1^1$, $\underline{y}_1^2(t) = \overline{y}_1^2$, and hence

$$y^{1}(0.2) = 1.22, y^{2}(0.2) = -0.82$$

Solving the crisp system using Euler method, gives:

$$y^{1}(0.2) = 1.31, y^{2}(0.2) = -0.86$$

Example (3.4):

Γο solve the following non-homogenous fuzzy system using

linearization technique,

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$$J = \begin{bmatrix} \frac{\partial y_1}{\partial y_2} & \frac{\partial y_2}{\partial y_1} \\ \frac{\partial f_2}{\partial y_1} & \frac{\partial f_2}{\partial y_2} \end{bmatrix} = \begin{bmatrix} 1 & -3 \\ -2 & 4 \end{bmatrix}$$

So, we get the following homogenous fuzzy system

$$\dot{\mathbf{y}} = \begin{bmatrix} 1 & -3 \\ -2 & 4 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}, \ y_1 \Box \tilde{\mathbf{1}}, \ y_2 \Box -\tilde{\mathbf{1}}.$$

So, if we let for simplicity

$$\underline{Y}_{\alpha_0}^1 = a = 1 - \sqrt{1 - \alpha} \qquad , \overline{Y}_{\alpha_0}^1 = b = 1 + \sqrt{1 - \alpha}$$
$$\underline{Y}_{\alpha_0}^2 = c = -1 - \sqrt{1 - \alpha} \qquad , \ \overline{Y}_{\alpha_0}^2 = d = -1 + \sqrt{1 - \alpha}$$

Now, Proceeding similarly as in example (3.3), we have:

$$B = \begin{bmatrix} 1 & -3i \\ -2i & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix} + \begin{bmatrix} 0 & -3i \\ -2i & 0 \end{bmatrix}$$
$$C = \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix}, \quad D = \begin{bmatrix} 0 & -3 \\ -2 & 0 \end{bmatrix}$$

and therefore,

$$\varphi(t) = \begin{bmatrix} e^{t} (1+3t^{2}+\frac{3}{2}t^{4}) & 0\\ 0 & 1+4t+11t^{2}+12t^{3}+\frac{51}{2}t^{4}+6t^{5}+12t^{6} \end{bmatrix}$$

Also,

$$\psi(t) = \begin{bmatrix} 0 & e^{t} (-3t^{3} - 3t) \\ -2t - 8t^{2} - 32t^{3} - 8t^{4} - 16t^{5} & 0 \end{bmatrix}$$

In special, for t = 0 we have:

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 $Y_{-\alpha}^{2}(0) = c, Y_{\alpha}^{2}(0) = d$

Also, for t = 1 we have:

$$\varphi(1) = \begin{bmatrix} 14.951 & 0 \\ 0 & 71.5 \end{bmatrix}$$
 and $\psi(1) = \begin{bmatrix} 0 & -16.31 \\ 66 & 0 \end{bmatrix}$

Also, by equation (3.20) we get:

$$\underline{Y}^{1}_{\alpha}(1) = (14.951)a + (-16.31)d$$

$$\overline{Y}^{1}_{\alpha}(1) = (14.951)b + (-16.31)c$$

$$\underline{Y}^{2}_{\alpha}(1) = (71.5)c + (66)b$$

$$\overline{Y}^{2}_{\alpha}(1) = (71.5)d + (66)a$$

<u>Remark (3.4):</u>

The solution of the non-homogenous fuzzy system (which is the linearized to the homogenous system) could be checked and compared with the exact non-homogenous crisp system;

Suppose $\alpha = 1$ for the solution of the non-homogenous fuzzy system, we have

$$Y(0) = \begin{bmatrix} Y_1(0) \\ Y_2(0) \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \quad Y(1) = \begin{bmatrix} Y_1(1) \\ Y_2(1) \end{bmatrix} = \begin{bmatrix} 31.261 \\ -5.5 \end{bmatrix}$$

Then the exact solution of the non-homogenous crisp system is:

$$Y(0) = \begin{bmatrix} Y_1(0) \\ Y_2(0) \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \quad Y(1) = \begin{bmatrix} Y_1(1) \\ Y_2(1) \end{bmatrix} = \begin{bmatrix} 31.332 \\ -5.467 \end{bmatrix}$$

We notice that the difference is negligible.

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non-homogenous) using the shooting method with some illustrative examples,

where the crisp solution for these examples is compared with the solution of the boundary value problem of crisp differential equations.

3.5.1 Boundary Value Problems of Fuzzy Differential Equations:

The boundary value problems whose equations are given with fuzzy initial conditions given at two or more points. When the fuzzy initial conditions are given at two points then the problem is called (a two point fuzzy boundary value problems).

We consider differential equations of order two with boundary fuzzy conditions at a and b.

The general problem of the second order is given by:

 $y'' = f(t, y, y'), \ a \le t \le b....(3.29)$

with boundary conditions

1- $y(a) \Box \tilde{\alpha}, y(b) \Box \tilde{\beta}.$ 2- $y'(a) \Box \tilde{\alpha}, y'(b) \Box \tilde{\beta}.$ 3- $v(a) \square \tilde{\alpha}, v'(b) \square \tilde{\beta}$ 4- $a_0 y(a) + a_1 y'(a) \square \tilde{\alpha}, \quad b_0 y(b) + b_1 y'(b) \square \tilde{\beta}.$

where a_0, b_0, a_1, b_1 are given constants and $\tilde{\alpha}, \tilde{\beta}$ are fuzzy numbers.

When f is linear in y and y' then we get a fuzzy boundary problem of

order two, The general form of a linear second order fuzzy boundary value

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2- A unique solution of the problem is assumed to be exist.

3.5.2 The Shooting Method for Solving Boundary Value Problems:

Consider the second order boundary value problems

$$y'' = P(t)y' + q(t)y + r(t), a < t < b$$

 $y(a) \Box \tilde{\alpha}, \quad y(b) \Box \tilde{\beta}.$

Consider the homogenous problem

(1) u'' = p(t)u' + q(t)u with $u(a) \square \tilde{0}, u'(a) \square \tilde{1}$.

Consider the non homogenous problem

(2) v'' = p(t)v' + q(t)v + r(t) with $v(a) \square \tilde{\alpha}, v'(a) \square \tilde{0}$.

Then the solution can be obtained using the previous discussed methods which are given by:

$$\underbrace{\underline{y}(t) = \underline{v}_1(t) + \underline{\lambda}\underline{u}_1(t)}_{\overline{y}(t) = \overline{v}_1(t) + \overline{\lambda}\overline{u}_1(t)}$$

where

$$\underline{\lambda} = \frac{\beta - \underline{v}_1(b)}{\underline{u}_1(b)}, \quad \overline{\lambda} = \frac{\overline{\beta} - \overline{v}_1(b)}{\overline{u}_1(b)}$$

Example (3.5):

To solve the homogenous fuzzy boundary value problem using the shooting method, where

 $y, \quad y(0) \square \tilde{1}, y(1) \square -\tilde{1} \quad , t \in [0,1]$

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$$\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & u_1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}, \quad u_1(0) \square \tilde{0}, u_2(0) \square \tilde{1}, \ t \in [0,1]$$

Now, applying the method of parametric representation mentioned in earlier, one will find the solution to be as follows:

Hence at t = 1

$$\underline{U}_{\alpha}^{1}(1) = a + c - b, \quad \overline{U}_{\alpha}^{1}(1) = b + d - a$$
$$\underline{U}_{\alpha}^{2}(1) = c - b, \quad \overline{U}_{\alpha}^{2}(1) = d - a$$

Where $a = -\sqrt{1-\alpha}$, $b = \sqrt{1-\alpha}$, $c = 1 - \sqrt{1-\alpha}$, $d = 1 + \sqrt{1-\alpha}$

Now, consider now the second problem

$$\begin{bmatrix} v_1' \\ v_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}, \quad v_1(0) \square \ \tilde{1}, v_2(0) \square \ \tilde{0}, \ t \in [0,1]$$

and for t = 1

$$\underline{V}^{1}_{\alpha}(1) = a + c - b, \quad \overline{V}^{1}_{\alpha}(1) = b + d - a$$
$$\underline{V}^{2}_{\alpha}(1) = c - b, \quad \overline{V}^{2}_{\alpha}(1) = d - a$$

where $a = 1 - \sqrt{1 - \alpha}$, $b = 1 + \sqrt{1 - \alpha}$, $c = -\sqrt{1 - \alpha}$, $d = \sqrt{1 - \alpha}$ Now

Now,

$$=\frac{\beta - V_1(b)}{U_1(b)} = \frac{-1 - (a + c - b)}{(a + c - b)}$$

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 $\underline{Y}(t) = V_1(t) + \underline{\lambda}\underline{U}_1(t), \quad Y(t) = V_1(t) + \lambda U_1(t).$

We can check the results by comparing with the crisp solution at $\alpha = 1$, and for t = 1, we have

 $\underline{Y}(1) = V_1(1) + \underline{\lambda U}_1(1) = -0.9992, \quad \overline{Y}(1) = \overline{V_1}(1) + \overline{\lambda U}_1(1) = -0.9992$

Where the crisp solution at t = 1 is: Y(1) = -1.

Also, we could make a good comparison between the crisp solution and fuzzy solution with $\alpha = 1$ in the next figure:

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Fig (3.5) A comparison between the crisp solution and fuzzy solution at $\alpha = 1$

Example (3.6):

To solve the non-homogenous fuzzy boundary value problems

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$$\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & u_1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}, \ u_1(0) \Box \ \tilde{0}, \ u_2(0) \Box \ \tilde{1}, \ t \in [0, 0.4]$$

So, the desired system is linear homogenous system of fuzzy initial value problem, and upon carrying out similar calculations in solving fuzzy differential equations, whenever for t = 0.4

$$\underline{U}_{\alpha}^{1}(0.4) = (1.08)a + (0.41)c, \quad \overline{U}_{\alpha}^{1}(0.4) = (1.08)b + (0.41)d$$
$$\underline{U}_{\alpha}^{2}(0.4) = (0.41)a + (1.08)c, \quad \overline{U}_{\alpha}^{2}(0.4) = (0.41)b + (1.08)d$$

where $a = -\sqrt{1-\alpha}$, $b = \sqrt{1-\alpha}$, $c = 1 - \sqrt{1-\alpha}$, $d = 1 + \sqrt{1-\alpha}$

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Also the non-homogenous problem:

$$v'' = v + 2t, \ v(0) \square \tilde{1}, \ v'(0) \square \tilde{0}$$

or in matrix form

$$\begin{bmatrix} v_1' \\ v_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 2t \end{bmatrix} = \begin{bmatrix} v_2 \\ v_1 + 2t \end{bmatrix} = \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

with $v_1(0) \Box \tilde{1}$, $v_2(0) \Box \tilde{0}$, $t \in [0, 0.4]$

So, the desired non-homogenous system of differential equations with fuzzy initial conditions could also be solved.

Solving the non-homogenous system using the linearization method.

$$\begin{bmatrix} v_1' \\ v_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 2t \end{bmatrix}, v_1(0) \square \tilde{1}, v_2(0) \square \tilde{0}, t \in [0, 0.4]$$

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Now, to find the value of $\underline{\lambda}$ and $\overline{\lambda}$:

$$\underline{\lambda} = \frac{B - V_1(b)}{\underline{U}_1(b)} = \frac{1.103 - (1.08a + 0.41c)}{(1.08a + 0.41c)}, \ \overline{\lambda} = \frac{B - \overline{V_1(b)}}{\overline{U}_1(b)} = \frac{1.103 - (1.08b + 0.41d)}{1.08b + 0.41d}$$

Hence, the general solution of fuzzy boundary value problem using shooting method is given by:

$$\underline{Y}(t) = \underline{V}_{1}(t) + \underline{\lambda}\underline{U}_{1}(t)$$
$$\overline{Y}(t) = \overline{V}_{1}(t) + \overline{\lambda}\overline{U}_{1}(t)$$

and at t = b = 0.4 with $\alpha = 1$, then

$$\underline{Y}(0.4) = V_1(0.4) + \underline{\lambda U}_1(0.4) = 1.103$$

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$$\overline{Y}(0.4) = \overline{V_1}(0.4) + \overline{\lambda}\overline{U}_1(0.4) = 1.103$$

Clearly, $\overline{y}(t)$ and y(t) are equal only when $\alpha = 1$ and when t = b.

Also, we can make a comparison between the crisp solution and the fuzzy solution with $\alpha = 1$, by the following figure:



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solve the nonlinear fuzzy boundary value problem using the shooting

method, where:

$$y'' = 2yy', \quad y(0) \Box -\tilde{1}, y(\pi/2) \Box -\tilde{1} \quad , t \in [0, \pi/2]$$

Hence the linearized system evaluated at (1/2, 0) is given by:

$$\begin{bmatrix} y_1' \\ y_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}, \quad y(0) \square -\tilde{1}, y(\frac{\pi}{2}) \square -\tilde{1}$$

Now, consider the first problem:

$$\begin{bmatrix} u_1' \\ u_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}, \quad u_1(0) \square \ \tilde{0}, u_2(0) \square \ \tilde{1}, \ t \in [0, \frac{\pi}{2}]$$

and upon applying the method of parametric representation mentioned earlier, one will find the solution to be as follows:

Hence at $t = \frac{\pi}{2}$ $\frac{U_{\alpha}^{1}(\pi/2)}{(\pi/2)} = a + (3.811)c, \overline{U}_{\alpha}^{1}(\pi/2) = b + (3.811)d$ $\frac{U_{\alpha}^{2}(\pi/2)}{(\pi/2)} = (4.811)c, \overline{U}_{\alpha}^{2}(\pi/2) = (4.811)d$ Where $a = -\sqrt{1-\alpha}, \ b = \sqrt{1-\alpha}, \ c = 1 - \sqrt{1-\alpha}, \ d = 1 + \sqrt{1-\alpha}$

Now, consider now the second problem

$$\begin{bmatrix} v_1' \\ v_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}, \quad v_1(0) \square -\tilde{1}, v_2(0) \square \tilde{0}, \ t \in [0, \frac{\pi}{2}]$$

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$$\underline{\lambda} = \frac{\beta - \underline{V_1}(b)}{\underline{U_1}(b)} = \frac{1 - (a + (3.811)c)}{(a + (3.811)c)}$$
$$\overline{\lambda} = \frac{\beta - \overline{V_1}(b)}{\overline{U_1}(b)} = \frac{1 - (b + (3.811)d)}{(b + (3.811)d)}$$

The general solution of FBVP using the shooting method is given by:

$$\underline{Y}(t) = \underline{V}_{1}(t) + \underline{\lambda}\underline{U}_{1}(t), \ \overline{Y}(t) = \overline{V}_{1}(t) + \overline{\lambda}\overline{U}_{1}(t)$$

We can check the results by comparing with the crisp solution at $\alpha = 1$, and for $t = \frac{\pi}{2}$, we have

$$\underline{Y}(\frac{\pi}{2}) = \underline{V}_{1}(\frac{\pi}{2}) + \underline{\lambda}\underline{U}_{1}(\frac{\pi}{2}) = -1, \qquad \overline{Y}(\frac{\pi}{2}) = \overline{V}_{1}(\frac{\pi}{2}) + \overline{\lambda}\overline{U}_{1}(\frac{\pi}{2}) = -1$$

Where the crisp solution at $t = \frac{\pi}{2}$ is: $Y(\frac{\pi}{2}) = -1$.

Also, we could make a good comparison between the crisp solution and fuzzy solution with $\alpha = 1$ in the next figure:



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Additional theoretical concepts in fuzzy set theory could be discussed concerning fuzzy mapping, differentiation and integration of fuzzy function, etc.; and therefore are presented in this chapter for completeness. This is a watermark for the trial version, register to get the full one!

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differentiation of fuzzifying function at a non-fuzzy point.

Finally, in section four two types of fuzzy integration have been discussed, which are integration of real valued fuzzy function over closed interval and integration of crisp real valued function over fuzzy interval since of it's important in the existence and uniqueness theorem of fuzzy differential equations.

2.1 FUZZY FUNCTIONS [DUBOIS, 1980]

The term "fuzzy function" must be understood in several ways according to where fuzziness occurs. We start first with the first type:

2.1.1 Function with Fuzzy Constraint:

Let X and Y be two universal sets and let f be a classical function $f: X \to Y$ maps from a fuzzy domain \widetilde{A} in X into a fuzzy range \widetilde{B} in Y then f is a function with fuzzy constraint if for all $x \in X$, $\mu_{\widetilde{B}}(f(x)) \ge \mu_{\widetilde{A}}(x)$.

Example(2.1):

Let X = Y = R, and consider two fuzzy sets:

$\widetilde{A} = \{(1,0.5), (2,0.8)\}$ and $\widetilde{B} = \{(2,0.7), (4,0.9)\}$

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independent variables to dependent variables, when f is a crisp function from

X onto *Y*. Let \tilde{A} be a fuzzy subset of *X*, then $\tilde{B} = f(\tilde{A})$ is a fuzzy subset of *Y* with membership function defined by:

$$\mu_{\tilde{B}}(y) = \begin{cases} \sup_{x \in f^{-1}(y)} \mu_{\tilde{A}}(x), & \text{if } f^{-1}(y) \neq \emptyset \\\\ 0, & \text{if } f^{-1}(y) = \emptyset \end{cases}$$

where $f^{-1}(y)$ is the inverse image of *y*.

Example (2.2):

Consider the universal sets X = Y = R and consider a crisp function $f(x) = x^2$, with the domain given by the fuzzy set:

 $\widetilde{A} = \{(-2, 0.9), (-1, 0.6), (0, 0.7), (1, 0.8), (2, 0.5)\},\$

The independent variable x has an ambiguity and the fuzziness which is propagated to the fuzzy set \tilde{B} , then we can obtain \tilde{B} , as:

 $\widetilde{B} = \{(4, 0.9), (0, 0.7), (1, 0.8)\}.$

2.1.3 Single Fuzzifying Function :

Fuzzifying function from X onto Y is a mapping from X into the fuzzy power set $\tilde{P}(Y)$ (or I^X), i.e., $\tilde{F}: X \to \tilde{P}(Y)$, that is to say the fuzzifying function is a mapping from an ordinary domain to a fuzzy set of range, This is a watermark for the trial version, register to get the full one!

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2.1.4 Fuzzy Bunch Function:

Fuzzifying bunch of crisp functions from *X* onto *Y* is defined with fuzzy set of crisp function:

$$\tilde{f} = \left\{ (f_i, \mu_{\tilde{f}}(f_i) | f_i : X \to Y, i \in N : N \text{ is the set of natural numbers} \right\}.$$

where $\mu_{\tilde{f}}(f_i)$ is the membership function of the crisp function f_i .

Example (2.3):

$$X = \{1, 2, 3\}, \ \widetilde{f} = \{(f_1, 0.4), (f_2, 0.7), (f_3, 0.5)\}$$

where $f_1(x) = x$, $f_2(x) = x^2$, $f_3(x) = 1 - x$.

2.2 FUZZY MAPPINGS

A fuzzy mapping is a generalization of the concept of a classical mapping which can be understood as follows:

Definition (2.1)[Dubois, 1982]:

A fuzzy mapping \tilde{f} from a crisp set U onto a set V is a mapping from U to the power set of non-empty subsets V, namely $\tilde{P}(V) - \{\emptyset\}$.

In other words, to each element $u \in U$ corresponds a fuzzy set $\tilde{f}(u)$ defined

on *V*, whose membership function is $\mu_{\tilde{f}(u)}$, and $\tilde{f}(u)$ is non-empty.

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- A fuzzy set \tilde{F} of V^U , i.e., a fuzzy set of ordinary mapping from U to Veach mapping $f: U \longrightarrow V$ is assigned a membership grade $\mu_{\tilde{F}}(f)$.

Proposition(2.1)[Dubois, 1982]:

A fuzzy mapping is strictly equivalent to a fuzzy relation \widetilde{R} such that

 $\forall u \in U, \exists v \in V, \quad \mu_{\tilde{\nu}}(u, v) = 0.$

Proof: See [Dubois, 1982]. ■

<u>Remarks (2.1):</u>

- 1. As a converse of proposition (2.1), a fuzzy relation can be viewed as a fuzzy mapping if $\mu_{\tilde{p}}(u,.)$ determines a nonempty fuzzy set $\tilde{f}(u)$.
- 2. Fuzzy mappings and fuzzy relations have different points of view on the same mathematical notion.
- 3. Fuzzy set of mappings (FSM's, for short) are not equivalent to fuzzy mapping. Indeed, a natural way of assigning membership grades μ(u,v) to possible images v∈ V of u∈ U, given an FSM F, is to define μ(u,v) = μ_F(f) whenever v = f(u). Note that μ(u,v) is not uniquely defined since there may exist f, g: U → V, f ≠g, such that

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Starting from the fuzzy mapping $f: U \to V$ for any $\alpha \in [0,1]$. We can

define an ordinary multimapping f_{α} as follows:

$$f_{\alpha}(u) \!=\! \left\{ v \mid \! \mu_{\tilde{f}(u)}(v) \!\geq\! \alpha \right\} \!\subseteq\! V \,, \, \text{for all } u \!\in\! U.$$

 f_{α} is the α - cut of \tilde{f} .

Also, f_{α} can be viewed as a crisp subset of V^{U} , i.e., a set of mappings

$$\begin{split} f_{\alpha} &= \Big\{ f: U \to V \mid \forall u \in U, f(u) \in f_{\alpha}(u) \Big\} \\ &= \Big\{ f: U \to V \mid \inf_{u \in U} \mu_{\tilde{f}(u)}(f(u)) \geq \alpha \Big\}. \end{split}$$

 f_{α} is the α -cut of an FSM generated by f_{α} , denoted $\gamma(\tilde{f})$, such that

Example(2.4) [Najeib S,W., 2002]:

Let $X = \{2, 3, 4, \dots, 25\}$, a fuzzy mapping \tilde{f} maps the elements in X to the power fuzzy set $\tilde{P}(X)$ in the following manner.

$$\begin{split} \widetilde{f}(2) &= \{(2,0.3), (3,0.5), (4,1), (5,0.5), (6,0.3), (9,0.2)\} \\ \widetilde{f}(3) &= \{(3,0.3), (5,0.5), (7,1), (9,0.5), (14,0.3), (16,0.2)\} \\ \widetilde{f}(4) &= \{(4,0.3), (8,0.5), (12,1), (16,0.5), (20,0.3), (25,0.2)\} \end{split}$$

Now, given a function $f_l(x) = 2x$,

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For $f_2(x) = x^2$, we have

$$\mu_{\gamma(\tilde{f})}(f) = \inf \left\{ \mu_{\tilde{f}(x)}(f_2(x)) | x \in X \right\}$$

= $\inf \left\{ \mu_{\tilde{f}(2)}(f_2(2)), \mu_{\tilde{f}(3)}(f_2(3)), \mu_{\tilde{f}(4)}(f_2(4)) \right\}$
= $\inf \left\{ \mu_{\tilde{f}(2)}(4), \mu_{\tilde{f}(3)}(9), \mu_{\tilde{f}(4)}(16) \right\}$
= $\inf \{1, 0.5, 0.5\} = 0.5$

So,
$$\gamma(\tilde{f}) = \{(f_1, 0), (f_2, 0.5)\}$$
, where $f_1(x) = 2x$ and $f_2(x) = x^2$.

Now, to the second case which is the converse of the above construction which is also can be made as expressed in the following definition.

Definition(2.2) [Najeib S.W., 2002]:

Given a fuzzy set of mappings $\gamma(\tilde{f})$ with $\mu_{\gamma(\tilde{f})}: I^x \to [0,1]$, we can construct a fuzzy mapping $\tilde{f}: X \to \tilde{P}(X)$ such that $\tilde{f}(x)$ is a fuzzy set with membership function defined as follows :

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 $T(f) = \{(f_1, 0.2), (f_2, 0.5), (f_3, 0.7), (f_4, 0.3)\}$

where

$$f_1(x) = x, f_2(x) = x^2, f_3(x) = e^x, f_4(x) = x + 1.$$

Then the image at x = 1, is:

$$\mu_{\tilde{f}(1)}(y) = \sup \left\{ \mu_{\gamma(\tilde{f})}(f) \mid y = f(x) \right\}$$

The possible values of y is $\{f_1(1), f_2(1), f_3(1), f_4(1)\} = \{1, 1, e, 2\}$

$$\mu_{\tilde{f}(1)}(y) = \sup_{f_1, f_2} \left\{ \mu_{\gamma(\tilde{f})}(f_1), \ \mu_{\gamma(\tilde{f})}(f_2) \right\}$$
$$= \sup_{f_1, f_2} \{ 0.2, 0.5 \} = 0.5$$

 $\mu_{\tilde{f}^{(1)}}(e) = 0.7, \ \mu_{\tilde{f}^{(1)}}(2) = 0.3$

So the fuzzy set $\tilde{f}(1) = \{(1,0.5),(2,0.3),(e,0.7)\}$

Similarly

$$\tilde{f}(2) = \{(2,0.2), (4,0.5), (e^2, 0.7), (3,0.3)\}$$

 $\tilde{f}(3) = \{(3,0.2), (9,0.5), (e^3, 0.7), (4,0.3)\}.$

Hence:

$$\widetilde{f}(x) = \left\{ \left(f(x), \sup\{\mu_{\gamma(\widetilde{f})}(f) \mid y = f(x), f \in \gamma(\widetilde{f})\} \right) \right\}, \text{ for all } x \in X.$$

Lemma (2.1) [Dubois, 1982]:

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inf min { $\mu_{\tilde{f}(u)}(f(u)), \mu_{\tilde{g}(u)}(g(u))$]

 $f,g:h(u)=f(u)+g(u) \ u\in U$

$$\leq \inf_{u \in U} \sup_{f,g:h(u)=f(u)+g(u)} \min \left(\mu_{\tilde{f}(u)}(f(u)), \mu_{\tilde{g}(u)}(g(u)) \right),$$

and since for any mapping $\varphi:A \times B \rightarrow R$.

 $\inf_x \sup_y \varphi(x,y) \ge \sup_x \inf_y \varphi(x,y),$

hence,

$$\begin{split} \mu_{\gamma(f)\oplus\gamma(g)}(\mathbf{h}(\mathbf{u})) &\leq \inf_{u\in U} \mu_{\gamma(f\oplus g)(u)}(h(u)) \\ &\leq \mu_{\gamma(\tilde{f}\oplus\tilde{g})(u)}h(u). \quad \blacksquare \end{split}$$

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2.3 FUZZY DIFFERENTIATION [DUBOIS, 1982]

The fuzzy differentiation depends on the type of the considered function in section (2.1), i.e., differentiation of non-fuzzy function over fuzzy interval and that of fuzzifying function at non-fuzzy points, may be considered as a type of fuzzy differentiation.

2.3.1 Differentiation of Crisp Function on Fuzzy Points:

By the extension principle, differentiation $f'(\tilde{A})$ of a non-fuzzy function f at fuzzy point \tilde{x}_0 [Dubois, 1982b] is defined as:

 $\mu_{f'(\tilde{x}_0)}(y) = Max \ \mu_{\tilde{x}_0}(x)$

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then $f'(x) = 3x^2$ and therefore:

$$f'(\widetilde{A}) = \{(3, 0.4), (0, 1), (3, 0.6)$$
$$= \{(3, 0.6), ((0, 1))\}$$

2.3.2 Differentiation of Fuzzifying Function Over a Set of Non-Fuzzy Points:

For all x belongs to the ordinary domain D, we will define the differentiation of fuzzifying function \tilde{f} at a non-fuzzy point. Let any α -cut of \tilde{f} be differentiable for an arbitrary x in D, we define differentiation $(d\tilde{f}/dx)(x_0)$ at an ordinary point x_0 as:

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$$\mu_{\left(d\tilde{f}/dx\right)(x_{0})}(p) = \max_{\left(d\tilde{f}_{\alpha}/dx\right)(x_{0})=p} \mu_{\tilde{f}}(\tilde{f}_{\alpha})$$

The next example illustrates the above definition:

Example (2.7):

Consider the fuzzifying function:

 $\tilde{f} = \{(f_1, 0.4), (f_2, 0.7), (f_3, 0.4)\}$

where f_1, f_2 and f_3 are crisp functions defined by:

$$f_1(x) = x, f_2(x) = x^2$$
 and $f_3(x) = x^3 + 1$

Then $f_1'(x) = 1, f_2'(x) = 2x$ and $f_3'(x) = 3x^2$

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$$f_3'(0.5) = 0.75$$
, when $\alpha = 0.4$.

Hence:

$$\frac{d\tilde{f}}{dx}(x_0) = \max\{(1, 0.4), (1, 0.7), (0.75, 0.4)\}\$$
$$=\{(1, 0.7), (0.75, 0.4)\}.$$

Another type of fuzzy differentiation which is called the *L- R type* could be used also in differentiating fuzzy functions (for more details, see, e.g., [Dubois, 1982]).

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2.3.3 Algebraic Properties of Differentiation

As in non-fuzzy differentiation so many properties are given and proved successfully. Therefore, similarly several algebraic properties undertaking fuzzy differentiation could be given. The proofs will be given here for the sake of completeness.

We start first with the following theorem:

<u>Theorem (2.1):</u>

The extended sum \oplus of the derivatives of the real valued functions *f* and *g* at the fuzzy point \tilde{x}_0 is defined by:

 $f'(\widetilde{x}_0) \oplus g'(\widetilde{x}_0) \supseteq (f' + g')(\widetilde{x}_0)$

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Theorem (2.2):

If f' and g' are continuous and both non-decreasing (or non-increasing), then:

 $f'(\widetilde{x}_0) \oplus g'(\widetilde{x}_0) = (f' + g')(\widetilde{x}_0)$

Proof: See [Dubois, 1982]. ■

The next theorem illustrates the differentiation of product of two functions, which is given in [Dubois, 1982] and other literatures without proof (to the best of our knowledge); which will be presented here for completeness:

Theorem (2.3):

1. If f and g are crisp functions from X to Y and \tilde{x}_0 is a fuzzy point in X then:

$$(fg)'(\widetilde{x}_0) = (f'g + fg')(\widetilde{x}_0) \subseteq [f'(\widetilde{x}_0) \square g(\widetilde{x}_0)] \oplus [f(\widetilde{x}_0) \square g'(\widetilde{x}_0)].$$

2. If f, g, f' and g' are continuous, f and g are both positive, and f' and g' are both non-decreasing (f, g are negative and f', g' are non decreasing), then:

$$(fg)'(\widetilde{x}_0) = [f'(\widetilde{x}_0) \Box g(\widetilde{x}_0)] \oplus [f(\widetilde{x}_0) \Box g'(\widetilde{x}_0)]$$

Proof:

1. According to the properties of fuzzy set, we must prove that:

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$$= \sup_{s,t:y=f'(s)g(s)+f(t)g'(t)} \min \left\{ \mu_{\tilde{x}_0}(s), \ \mu_{\tilde{x}_0}(t) \right\} ..(2.3)$$

Also, using the extension principle to the left hand side, one can get:

Now, from equations (2.3) and (2.4), we have:

٦

r

$$\sup_{x:y=f'(x)g(x)+f(x)g'(x)} \mu_{\tilde{x}_0}(x) \le \sup_{s,t:y=f'(s)g(s)+f(t)g'(t)} \min\left\{\mu_{\tilde{x}_0}(s), \ \mu_{\tilde{x}_0}(t)\right\}$$

Since $\tilde{x_0}$ is a fuzzy point which has a supremum value therefore,

$$(fg)'(\widetilde{x}_0) = (f'g + fg')(\widetilde{x}_0) \subseteq [f'(\widetilde{x}_0) \square g(\widetilde{x}_0)] \oplus [f(\widetilde{x}_0) \square g'(\widetilde{x}_0)].$$

2. Since f' and g' are continuous on [a, b] and both non decreasing in [a, b], then:

$$\forall s, \forall t > s, \exists x \in [s,t] \subseteq [a,b]$$
, such that:

$$f'(x) g(x) + f'(x) g'(x) = f'(s) g(s) + f(t) g'(t).$$

Hence in particular:

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$$\mu_{\tilde{x}_0}(x) \geq \min\left\{\mu_{\tilde{x}_0}(s), \mu_{\tilde{x}_0}(t)\right\}$$

Hence:

$$\mu_{\left[f'(x_0')\square g(\tilde{x_0})\right] \oplus \left[f(\tilde{x_0})\square g'(\tilde{x_0})\right]}(y) =$$

$$\sup_{\substack{u,v:y=u+v \\ x:y=f'(x)g(x)+f(x)g'(x) \\ x:y=f'(x)g(x)+f(x)g'(x) \\ x:y=f'(x)g(x) \\ x:y=f'(x)g(x) \\ x:y=f'(x)g(x) \\ x:y=f'(x)g'(x) \\ x:y=f'(x)g'(x)g'(x) \\ x:y=f'(x)g'(x) \\ x:y=f'(x)g'(x)g'(x) \\ x:y=f'(x)g'(x$$

$$= \sup_{x:y=f'(x)g(x)+f(x)g'(x)} \mu_{\tilde{x}_0}(x).$$

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Therefore;

$$\mu_{[f'(x_0')\square g(\tilde{x_0})] \oplus [f(\tilde{x_0})\square g'(\tilde{x_0})]}(y) = \sup_{x: y = f'(x)g(x) + f(x)g'(x)} \mu_{\tilde{x_0}}(x).$$

But;

$$\mu_{(f,g)'(\tilde{x}_0)}(y) = \mu_{[f',g+f,g'](\tilde{x}_0)}(y) = \sup_{x:y=f'(x),g(x)+f(x),g'(x)} \mu_{\tilde{x}_0}(y)$$

Then:

$$(f g)'(\tilde{x}_0) = [f'(\tilde{x}_0) \Box g(\tilde{x}_0)] \oplus [f(\tilde{x}_0) \Box g'(\tilde{x}_0)]. \blacksquare$$

2.4 FUZZY INTEGRATION

The fuzzy integration is one of the most important part of the analysis of This is a watermark for the trial version, register to get the full one!

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Integration of real fuzzy function over fuzzy interval.

The first two of the above three types will be discussed next:

2.4.1 Integration of Real Fuzzy Function over Crisp Closed Interval

[Dubois, 1982]

We shall now consider a fuzzy function f, which shall be integrated over the crisp interval [*a*,*b*].

Definition(2.3):

Let $\tilde{f}: X \to \tilde{F}(\mathbb{R})$, the integral of \tilde{f} over X = [a,b] denoted by $\int_{\mathbb{R}} \tilde{f}(t) dt$ is defined levelwise, as follows:

$$\left(\int_{X} \tilde{f}(t)dt\right)_{\alpha} = \int_{X} f_{\alpha}(t)dt, \text{ for all } 0 \le \alpha \le 1$$
$$= \left(\int_{X} f_{\alpha^{-}}(t)dt, \int_{X} f_{\alpha^{+}}(t)dt\right)....(2.5)$$

Remark (2.2):

If the fuzzy integration over the interval X = [a,b] is reversed from *b* to *a*. This is a watermark for the trial version, register to get the full one!

Benefits for registered users: 1.No watermark on the output documents. 2.Can operate scanned PDF files via OCR. 3.No page quantity limitations for converted PDF files. where $-\int \tilde{f}$ has for a membership function $\mu_{a}(u) = \mu_{b}(-u)$.

Following, some properties of the integration of fuzzy function over crisp interval which are given in [Dubois, 1982].

1.
$$\int_{X} (\tilde{f} \oplus \tilde{g}) \supseteq \left(\int_{X} \tilde{f} \right) \oplus \left(\int_{X} \tilde{g} \right)$$
, where \tilde{f} and \tilde{g} are real fuzzy functions from

the closed interval X to R, with bounded support.

2. Under the commutativity condition for \int_X and \oplus ,

$$\int_{X} (\tilde{f} \oplus \tilde{g}) = \left(\int_{X} \tilde{f} \right) \oplus \left(\int_{X} \tilde{g} \right)....(2.6)$$

Example(2.8):

Consider the bunch fuzzy function given in (2.1.4), by:

$$\tilde{f} = \{(f_1, 0.4), (f_2, 0.7), (f_3, 0.4)\}$$

where

$$f_1(x) = x, f_2(x) = x^2, f_3(x) = x+1$$

and to integrate this bunch function over [1,2], we perform this as follows:

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Hence, the integration result is with possibility 0.7, is given by:

$$\tilde{I}_{0.7}(1,2) = \{(\frac{7}{3}, 0.7)\}.$$

ii) Integration at $\alpha = 0.4$, there are two functions

$$f^{+} = f_1(x) = x$$
 and $f^{-} = f_3(x) = x+1$, then for

$$I^{+}_{\alpha}(1,2) = \int_{1}^{2} x dx = \frac{1}{2} x^{2} \bigg]_{1}^{2} = \frac{3}{2}.$$

and

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$$I_{\alpha}^{-}(1,2) = \int_{1}^{2} (x+1)dx = \frac{1}{2}x^{2} + x \bigg]_{1}^{2} = \frac{5}{2}$$

The integration results are with possibility 0.4. Then,

$$\tilde{I}_{0.4}(1,2) = \{(\frac{3}{2}, 0.4), (\frac{5}{2}, 0.4)\}.$$

Finally, we have the total integration.

$$\tilde{I}(1,2) = \{(\frac{7}{3}, 0.7), (\frac{3}{2}, 0.4), (\frac{5}{2}, 0.4)\}$$

2.4.2 Integration of a (Crisp) Real Valued Function Over a Fuzzy Interval

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rmalized convex fuzzy sets. The membership function

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 \tilde{b} D. If a_0 and b_0 are the lower/upper limits of the supports of \tilde{a} or \tilde{b} , then

 a_0 or b_0 are related to each other by $\underline{a}_0 = \text{Inf } S(\tilde{a}) \leq \text{Sup } S(\tilde{b}) = b_0$.



Fig.(2.6) Fuzzily bounded interval.

Definition (2.4)[Klir, G. J., 2000]:

Let *f* be a real valued function which is integrable in the interval $J = [a_0, b_0]$, then according to the extension principle the membership function of the fuzzy integral $\int f$ is given by:

$$\mu_{\int_{\widetilde{D}}^{f}}(z) = \sup_{x, y \in J: z = \int_{f}^{y}} Min \{\mu_{\widetilde{a}}(x), \mu_{\widetilde{b}}(y)\}.$$

Some Properties of The Integration of Crisp Function over Fuzzy Interval

[Klir, G. J., 2000]:

1. Let f be any function $f: D \rightarrow R$, which is integrable on D, then:

$\int f = F(\tilde{b}) \Theta F(\tilde{a}).$

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where Θ denotes the extended subtrac

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where \subseteq denotes the usual fuzzy set inclusion ($\tilde{A} \subseteq \tilde{B} \Leftrightarrow \mu_{\tilde{A}} \leq \mu_{\tilde{B}}$) and \oplus denotes the extended addition.

3. If
$$f, g: I \longrightarrow R^+$$
 or $f, g: I \longrightarrow R^-$, then:

$$\int_{a}^{b} (f+g) = \int_{a}^{b} f \oplus \int_{a}^{b} g$$

The following examples illustrate fuzzy integration and its properties:

Example (2.9):

Let:

$$\tilde{a} = \{(4, 0.8), (5, 1), (6, 0.4)\}$$

$$\tilde{b} = \{(6, 0.7), (7, 1), (8, 0.2)\}$$

and, $f(x) = 2, x \in [a_0, b_0] = [4, 8]$

The problem is to find the fuzzy integration of f(x) over J = [4, 8]. The following table illustrate these results.

Table (2.1)

Integration of f(x)=2, over an interval (a,b) with membership function

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(4, 8)	8	0.2
(5, 6)	2	0.7
(5, 7)	4	1.0
(5, 8)	6	0.2
(6, 6)	0	0.4
(6, 7)	2	0.4
(6, 8)	4	0.2

and by using the definition (2.4), then:

$$\int_{\tilde{D}} f = \{(0, 0.4), (4, 0.7), (4, 1), (6, 0.8), (8, 0.2)\}.$$

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Example (2.10):

Let:

$$f(x) = 2x - 3, g(x) = -2x + 5$$

and

$$\widetilde{a} = \{(1, 0.8), (2, 1), (3, 0.4)\}\$$

 $\widetilde{b} = \{(3, 0.7), (4, 1), (5, 0.3)\}$

so:

$$\int_{a}^{b} f(x) dx = x^{2} - 3x |_{a}^{b} = (b^{2} - 3b) - (a^{2} - 3a).$$

 $\left[g(x) \, dx = -x^2 + 5x \right]_{a}^{b} = (-b^2 + 5b) - (-a^2 + 5a).$

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$$\int_{\tilde{a}}^{\tilde{a}} g = \{(-6, 0.3), (-4, 0.3), (-2, 1), (0, 0.8), (2, 0.7)\}$$

$$\int_{\tilde{a}}^{\tilde{b}} f \oplus \int_{\tilde{a}}^{\tilde{b}} g = \{(-6, 0.3), (-4, 0.3), (-2, 0.4), (0, 0.7), (2, 0.7), (4, 1), (6, 0.8), (8, 0.7), (10, 0.3), (12, 0.3), (14, 0.3)\}$$

$$\int_{\tilde{a}}^{\tilde{b}} (f + g) = \{(0, 0.4), (2, 0.7), (4, 1), (6, 0.8), (8, 0.3)\}$$

and it is clear that:

$$\int_{\tilde{a}}^{\tilde{b}} f \oplus \int_{\tilde{a}}^{\tilde{b}} g \supseteq \int_{\tilde{a}}^{\tilde{b}} f + \int_{\tilde{a}}^{\tilde{b}} g.$$

40

CONCLUSIONS AND RECOMMENDATIONS -----

From the present work, the following conclusions are drawn:

- 1. All observed examples are defined on intervals which are belong to R^+ .
- 2. Up to our knowledge boundary value problems haven't been discussed before, especially methods of solution.
- 3. The method of successive approximations can be used to solve those problems in which the fuzziness appears in the solution and the kernel functions as a bunch fuzzy function.

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Using the collocation or the finite difference method for solving fuzzy

boundary value problems.

- 4. Studying the variational formulation of fuzzy boundary value problems.
- 5. Studying new types of fuzzy differential equations with fractional derivatives.

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INTRODUCTION -

Every day life, we use so many properties which cannot be dealt with satisfactory on a simple "Yes" or "No" answers, i.e., mathematically either belongs or not. Such properties perhaps are best indicated by shade of gray, rather than by in the black or white. Assigning each individual in a set (called the universal set and is denoted by X) on a "Yes" or "No" values as in ordinary set theory, is not an adequate way for dealing with such type of problems [Zadeh L.A., 1965].

Zadeh L.A., in 1965 introduced the subject of fuzzy set theory in which he considered the class of objects with continuum grads of membership, such

a set is characterized by a membership or characteristic function which

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thematics, while inexact structures encounter us in real life problems

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[Zaden L.A., 1905].

This thesis consists of three chapters.

Chapter one entitled (Fundamental Concepts in Fuzzy Sets) consist of seven sections. Section one consists of basic concepts and definitions related to fuzzy set theory which are necessary for the completeness of this thesis. Section two stands for studying different methods for constructing membership function numerically and analytically. In section three a study to the extension principle is given which is necessary for extending non-fuzzy concepts to fuzzy logic. In section four, and because of their importance in solving fuzzy differential equations, we study the α - level sets, as well as, some of it's properties. Finally, in sections five, six and seven we study

convex fuzzy sets, fuzzy relations and fuzzy number, respectively, which are necessary for the study of initial conditions of fuzzy differential equations.

Chapter two, entitled (Theoretical Results in Fuzzy Sets) consist of four sections. In section one, three types of fuzzy function have been discussed with some basic properties of such type of functions. In section two, we introduce the concept of fuzzy mapping with some related properties and propositions. In section three, differentiation of fuzzy function have been discussed with some basic algebraic properties. In section four we study the concept of fuzzy integration since of it's important in the existence and uniqueness theorem of fuzzy differential equations.

Finally, chapter three entitled (Solution of Fuzzy Differential Equations) consist of five sections. In section one, we introduce the concept of fuzzy

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solve the non-homogenous and nonlinear fuzzy initial value problems. In

section five an introduction to the solution of fuzzy differential equations with boundary conditions is presented using the shooting method to solve numerically boundary value problems.

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اللَّهُ ذُورُ آلسَّمَاوَاتِ وَالأرض مَثَلُ ذُورِهِ كَمِشْكَاةٍ فِيهَا مِصْبَاحٌ ٱلمِصْبَاحُ فِي زُجَاجَةٍ

ٱلزُّدَادَةُ كَأَنَّهَا كُوكُرُحُ حُرِّيٌّ بُوقَدُ مِن شَجَرَةِ

اللهُ لِنُورِهِ مَن يَشَاءُ وَيَضربُ اللَّهُ الأَمَثَالَ لِلنَّا

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وَٱللَّهُ بِكُل شَى عَلِيمُ

سورة النور، الأية ٣٥

المستخلط

إن احد اهداف در اسة موضوع نظرية المجموعات الضبابية هو لتطوير اساليب صياغة و حل المسائل التي تكون على درجة كبيرة من التعقيد او تلك التي تكون ذات تعريف غير دقيق وذلك لكي تكون مقبولة عند التعامل معها بالطرق التحليلية المألوفة. ولذلك يمكن اعتبار الضبابية على انها نوع من انواع اللادقة التي تواجهنا عند ايجاد الصياغة الرياضية لمسألة عملية والتي يكون فيها نوع من الغموض. هذا النوع من المجموعات استحدث من قبل العالم زاده في عام ١٩٦٥ كاسلوب لمعالجة هذا الغموض او اللادقة في النماذج الرياضية.

لهذه الأطروحة ثلاثة اهداف

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